

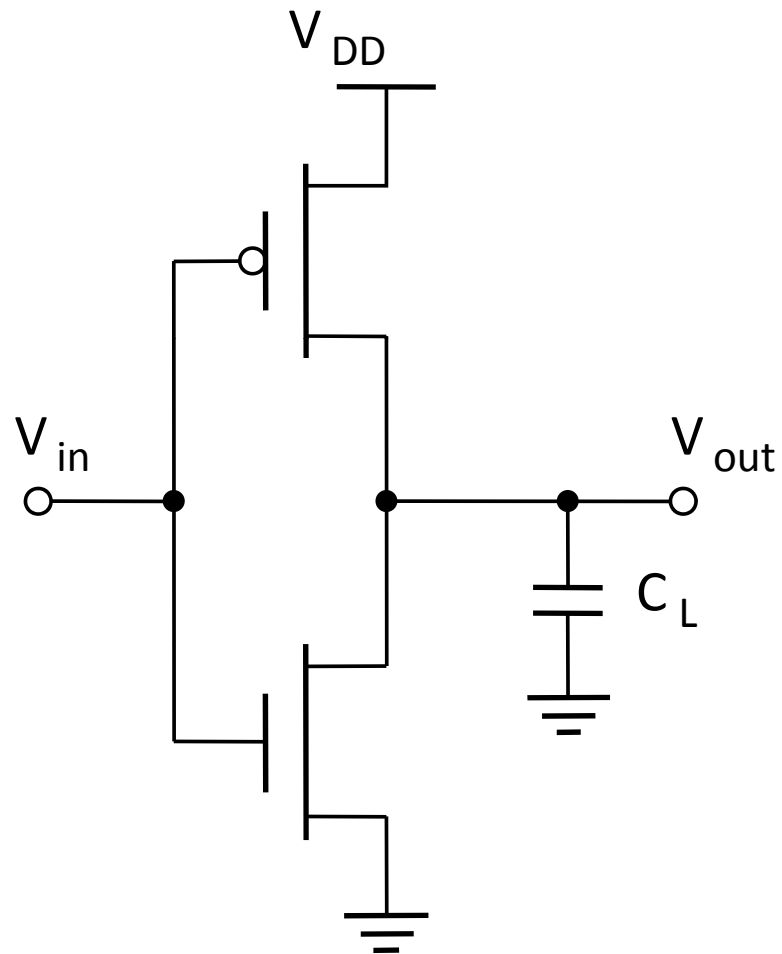
ECE680: Physical VLSI Design

Chapter III

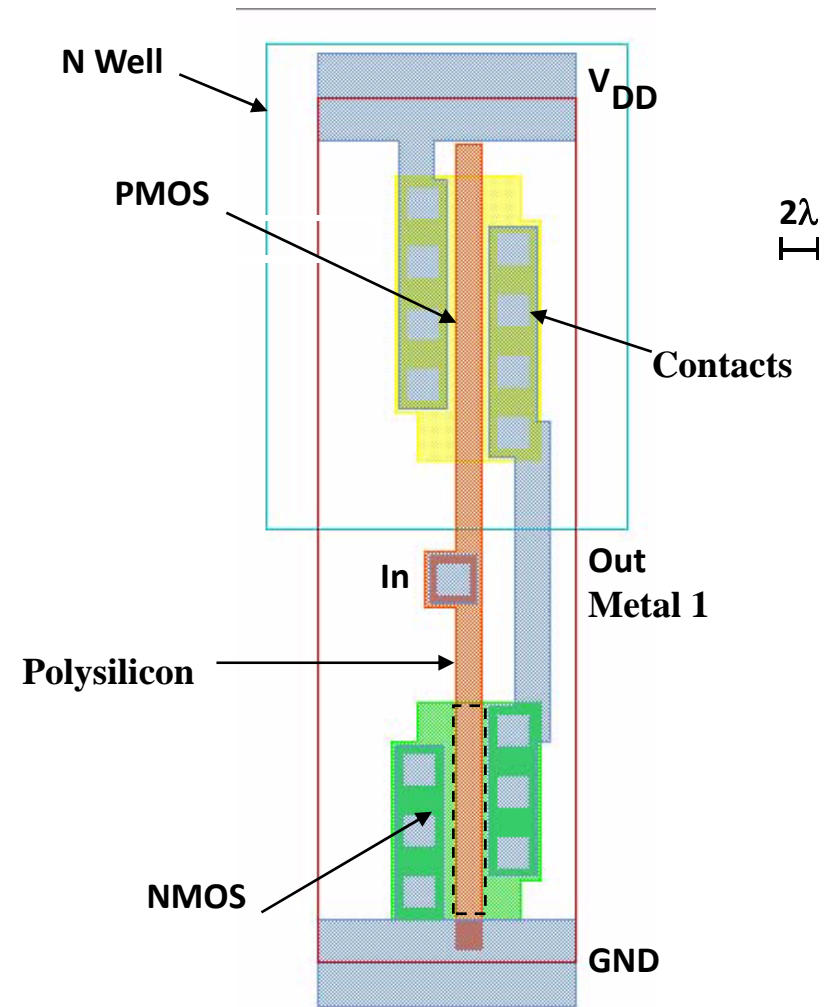
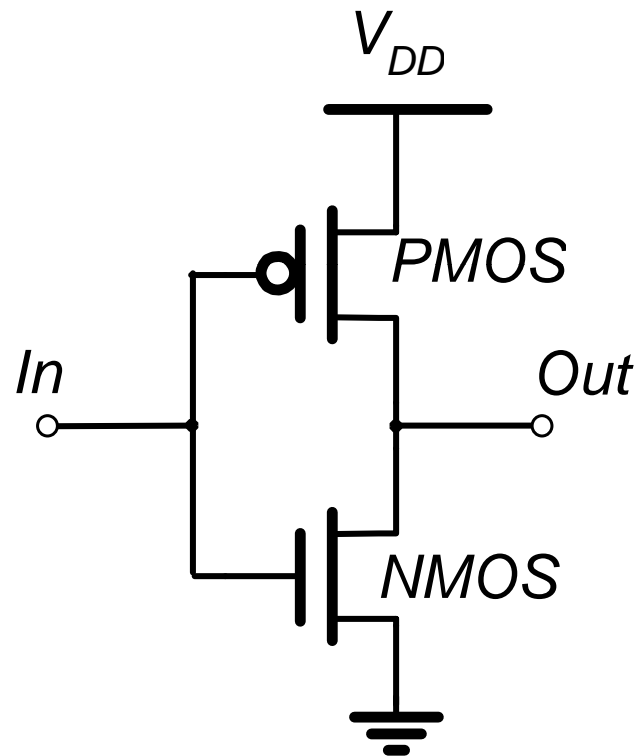
CMOS Device, Inverter, Combinational circuit Logic and Layout

Part 2 CMOS Inverter

The CMOS Inverter: A First Glance



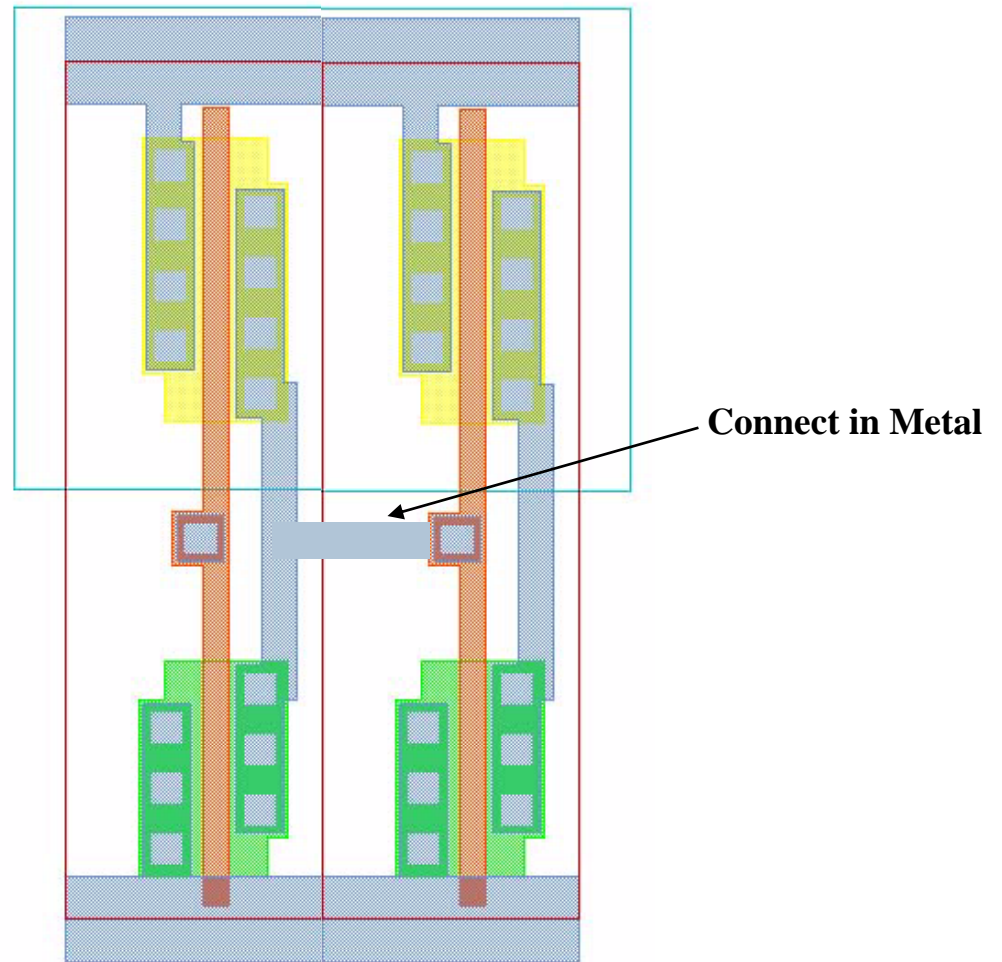
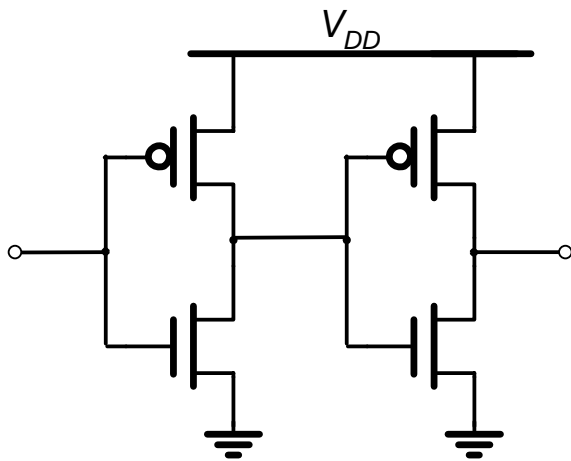
CMOS Inverter



Two Inverters

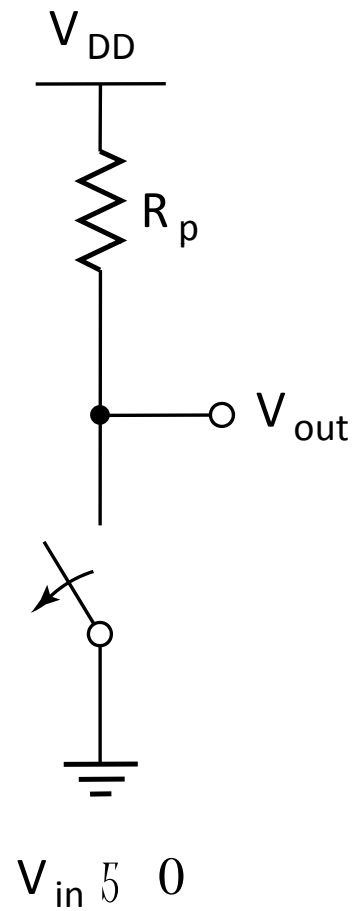
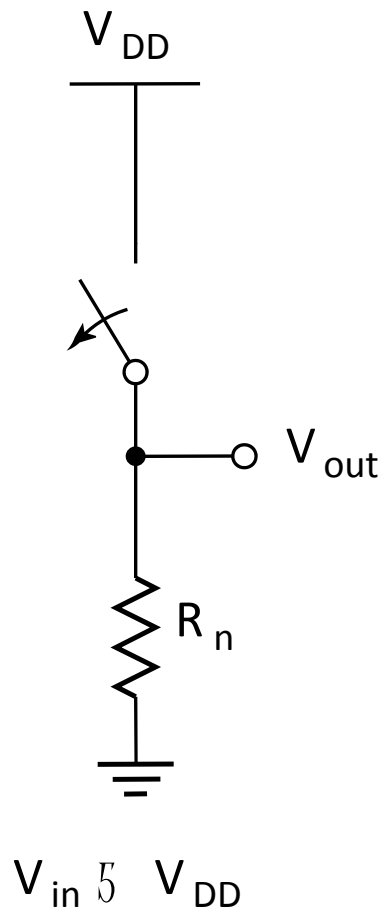
Share power and ground

Abut cells



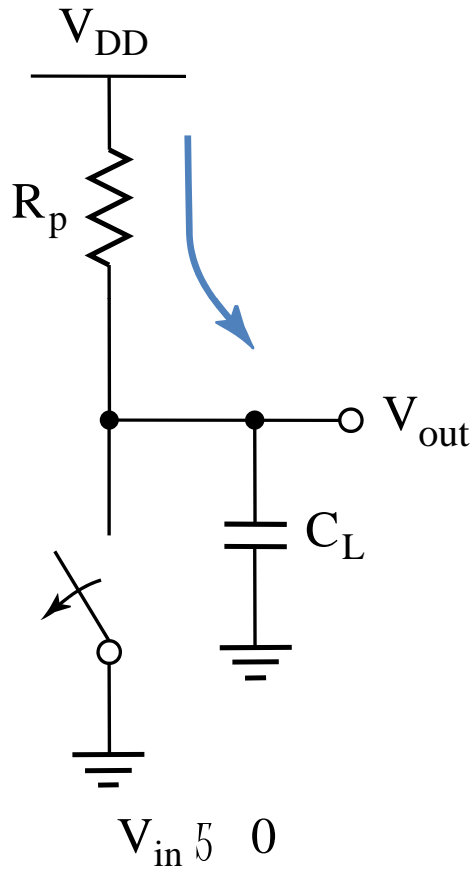
CMOS Inverter

First-Order DC Analysis

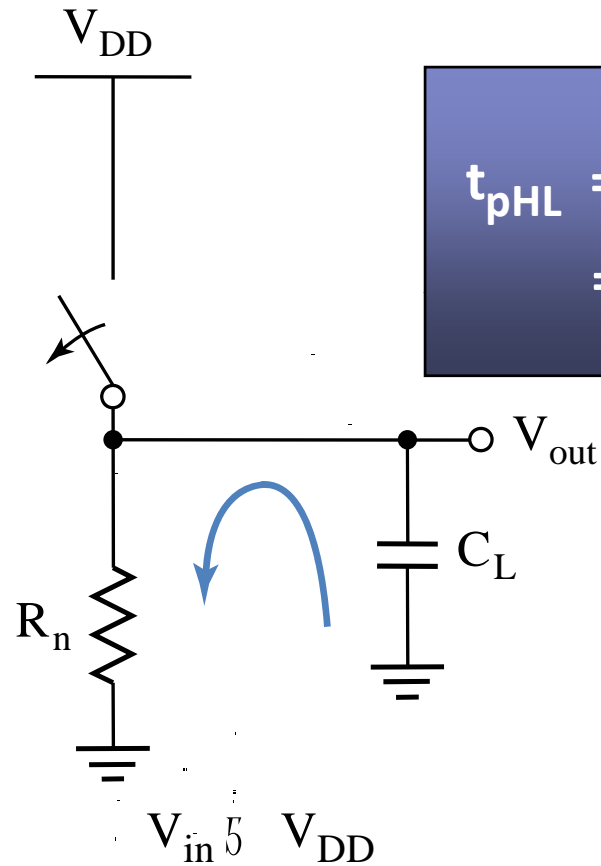


$$\begin{aligned} V_{OL} &= 0 \\ V_{OH} &= V_{DD} \\ V_M &= f(R_n, R_p) \end{aligned}$$

CMOS Inverter: Transient Response



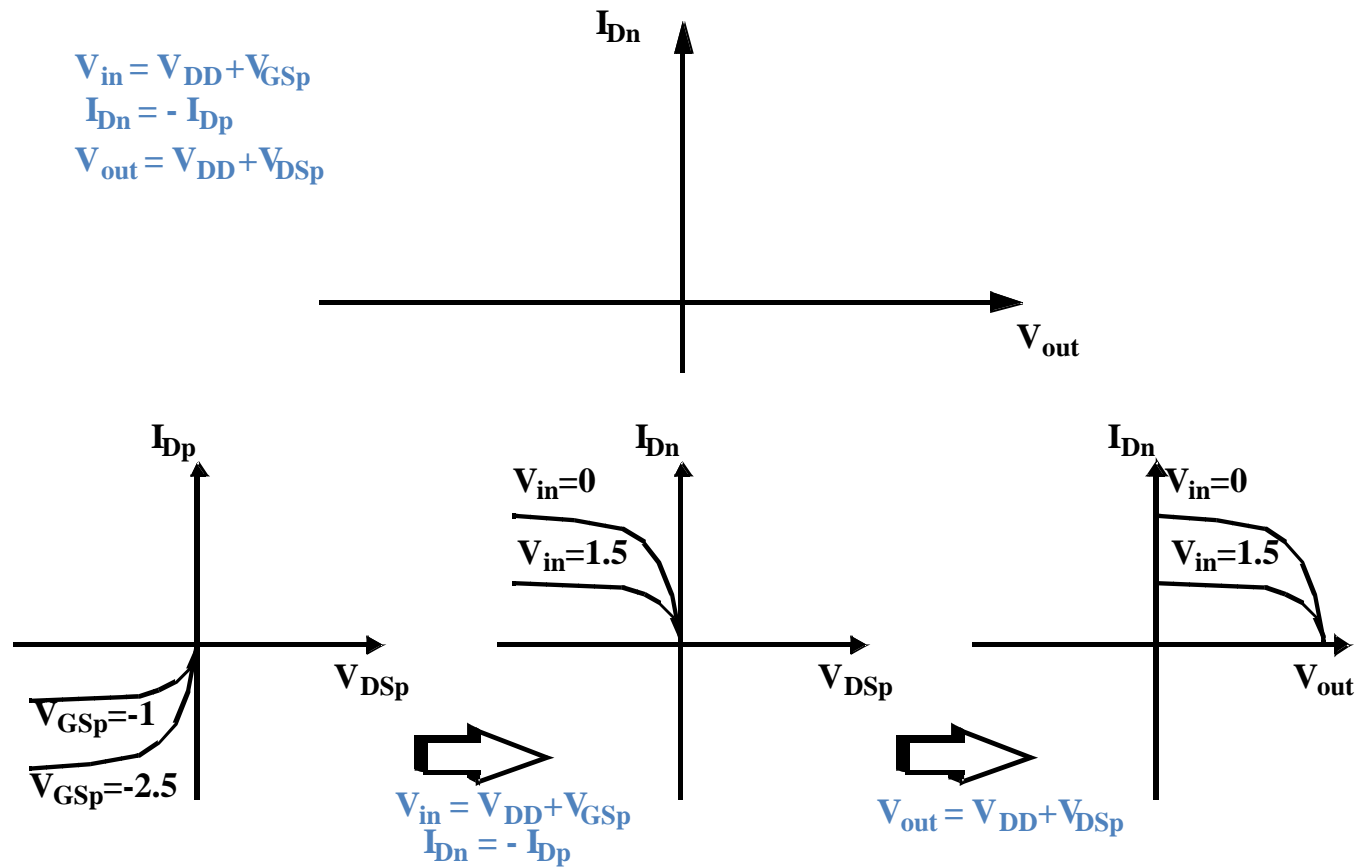
(a) Low-to-high



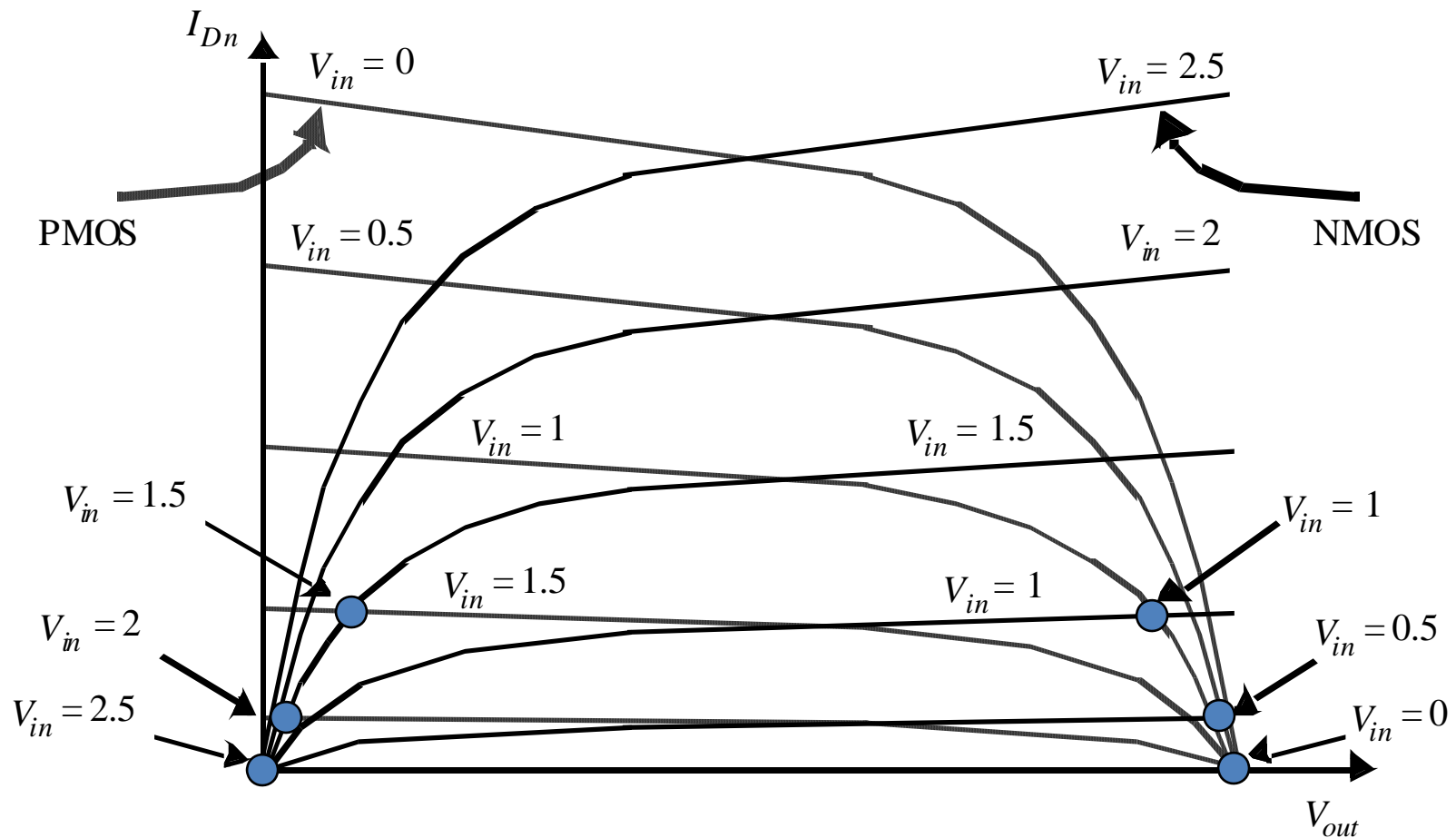
(b) High-to-low

$$t_{pHL} = f(R_{on} \cdot C_L) = 0.69 R_{on} C_L$$

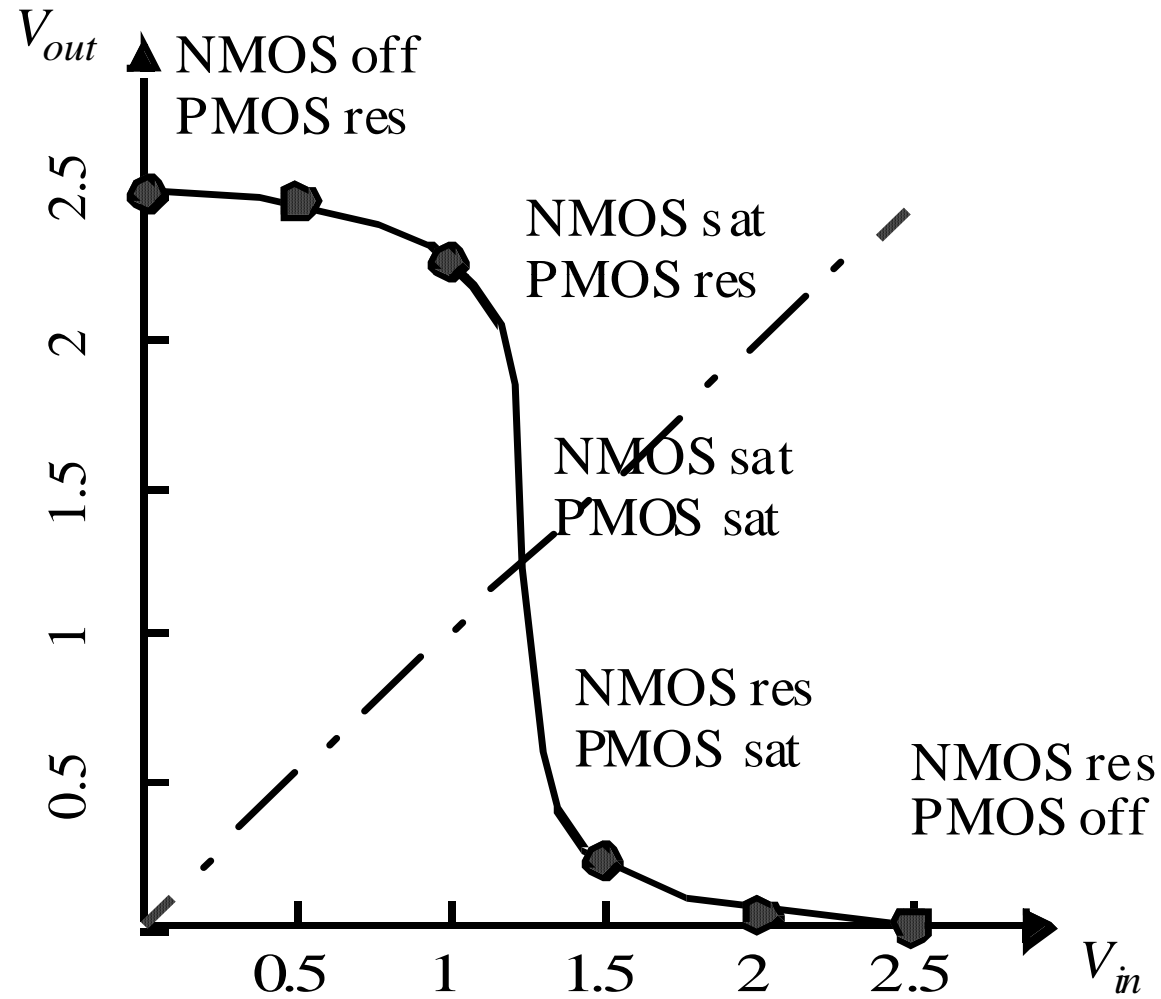
1. Voltage Transfer Characteristic PMOS Load Lines



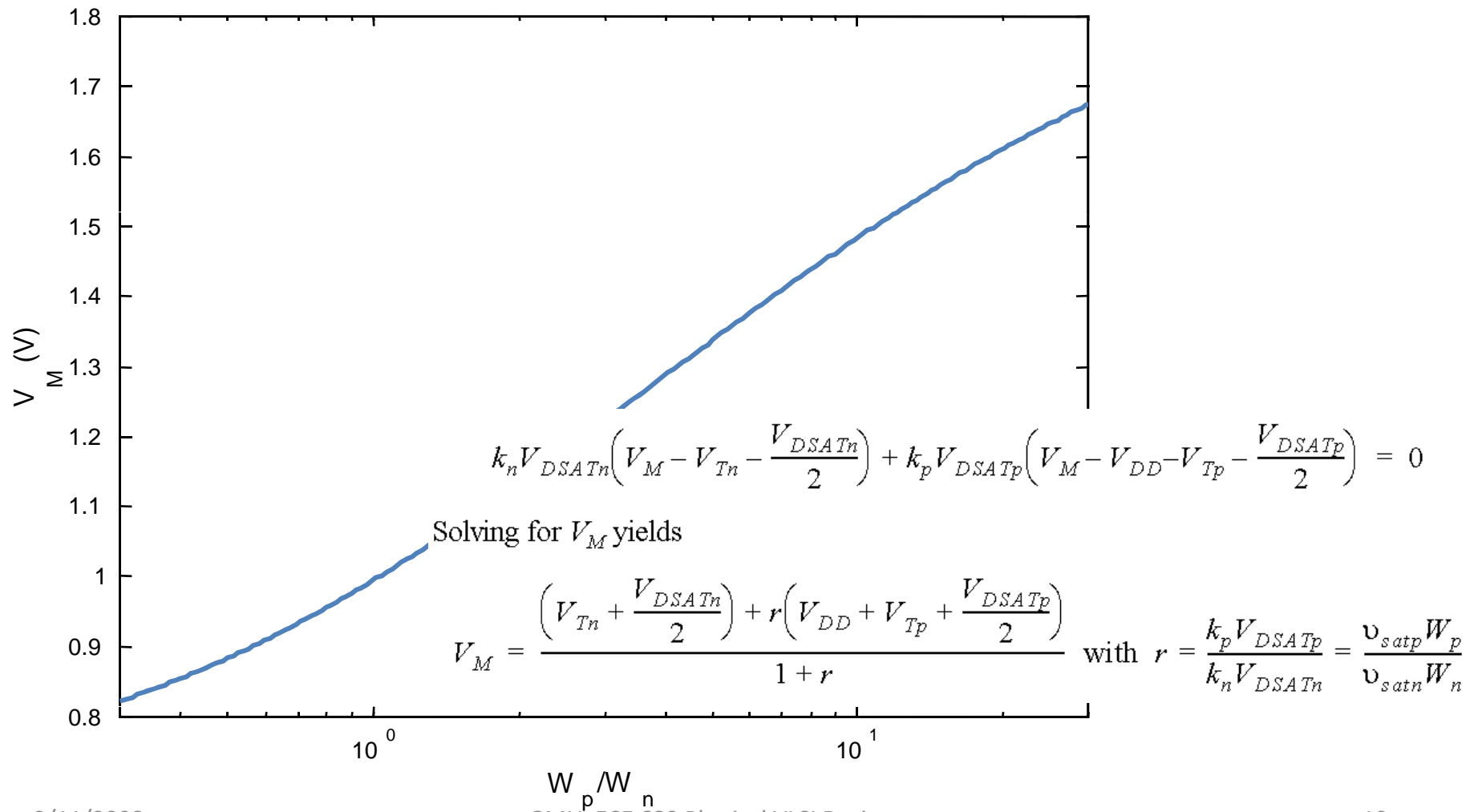
CMOS Inverter Load Characteristics



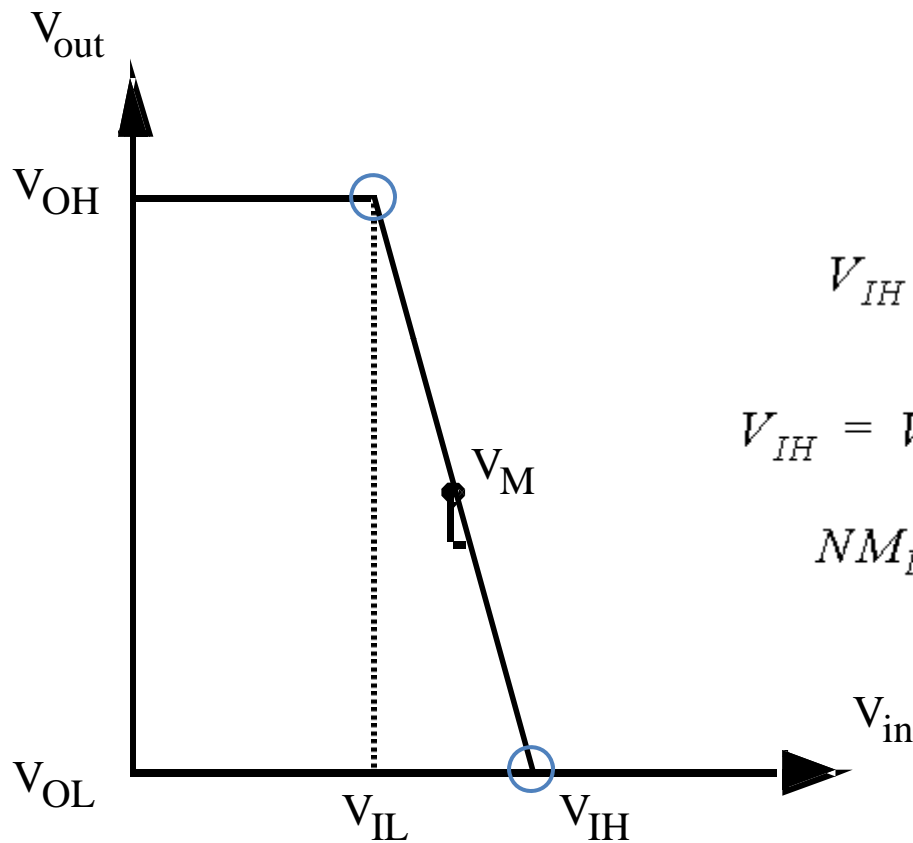
CMOS Inverter VTC



Switching Threshold as a function of Transistor Ratio



Determining V_{IH} and V_{IL}



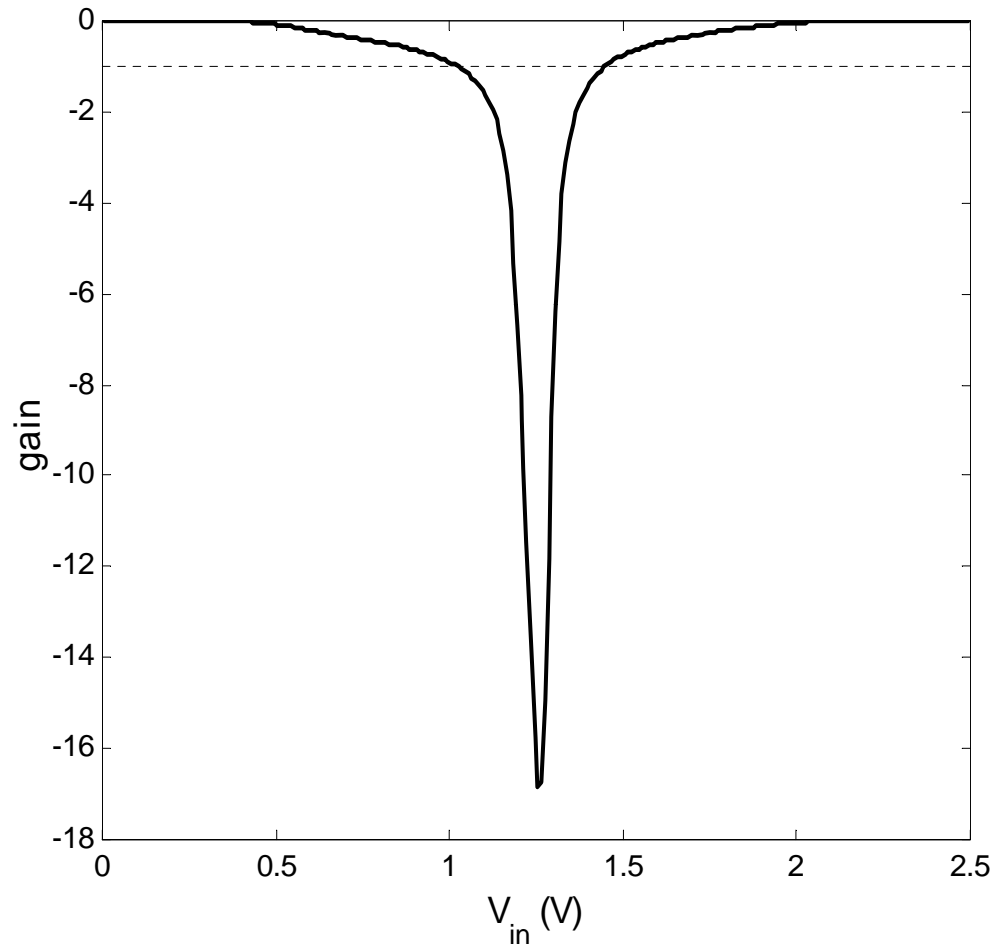
$$V_{IH} - V_{IL} = -\frac{(V_{OH} - V_{OL})}{g} = \frac{-V_{DD}}{g}$$

$$V_{IH} = V_M - \frac{V_M}{g} \quad V_{IL} = V_M + \frac{V_{DD} - V_M}{g}$$

$$NM_H = V_{DD} - V_{IH} \quad NM_L = V_{IL}$$

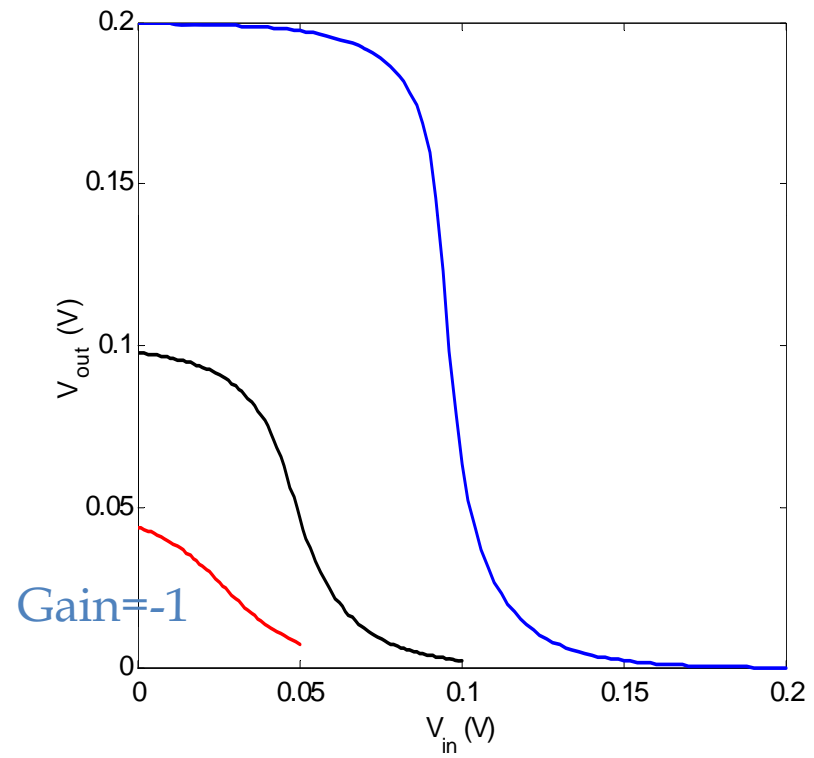
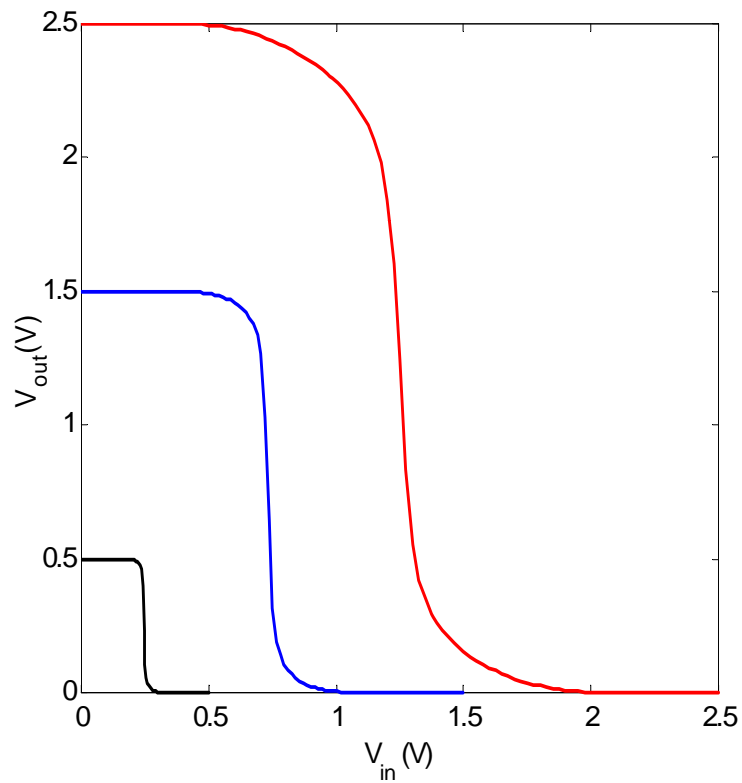
A simplified approach

Inverter Gain

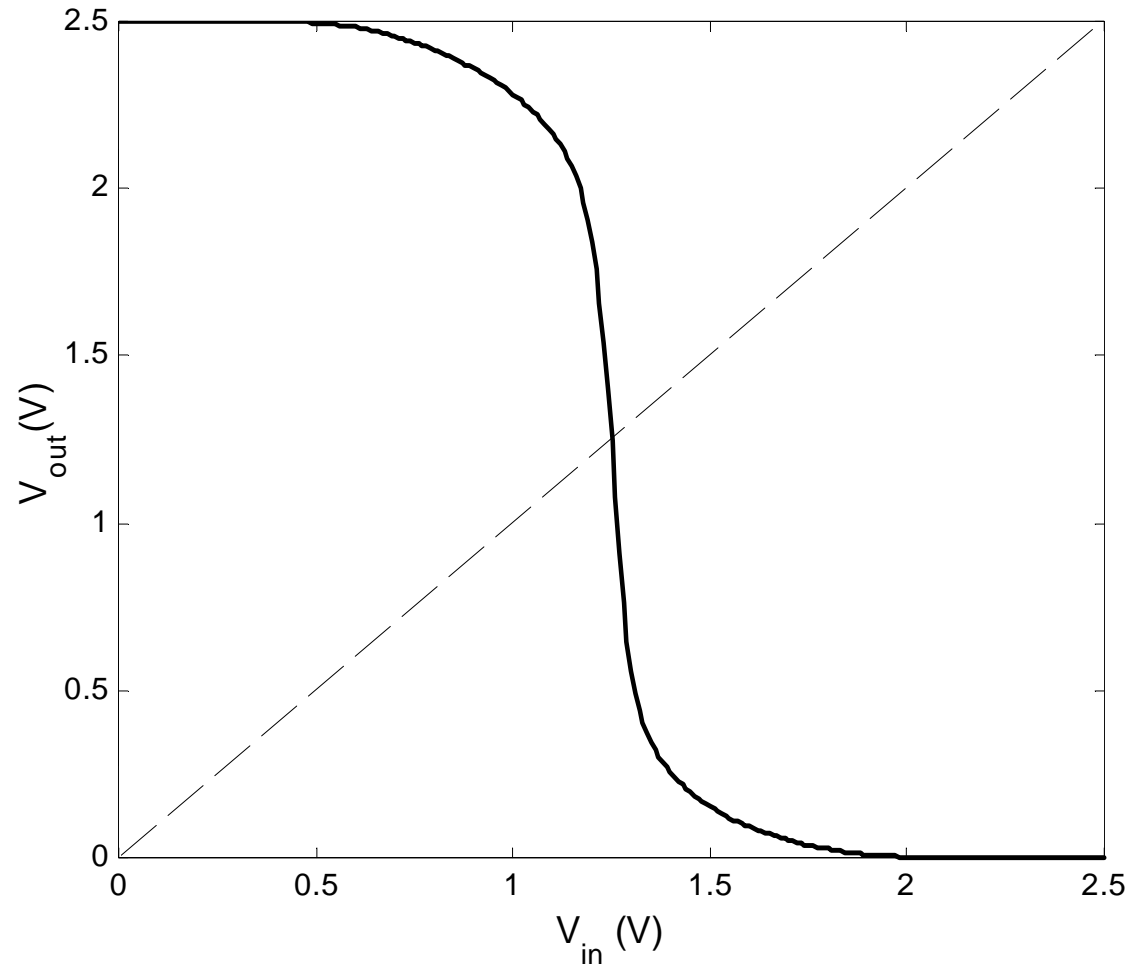


$$g = -\frac{1}{I_D(V_M)} \frac{k_n V_{DSATn} + k_p V_{DSATp}}{\lambda_n - \lambda_p}$$
$$\approx \frac{1+r}{(V_M - V_{Tn} - V_{DSATn}/2)(\lambda_n - \lambda_p)}$$

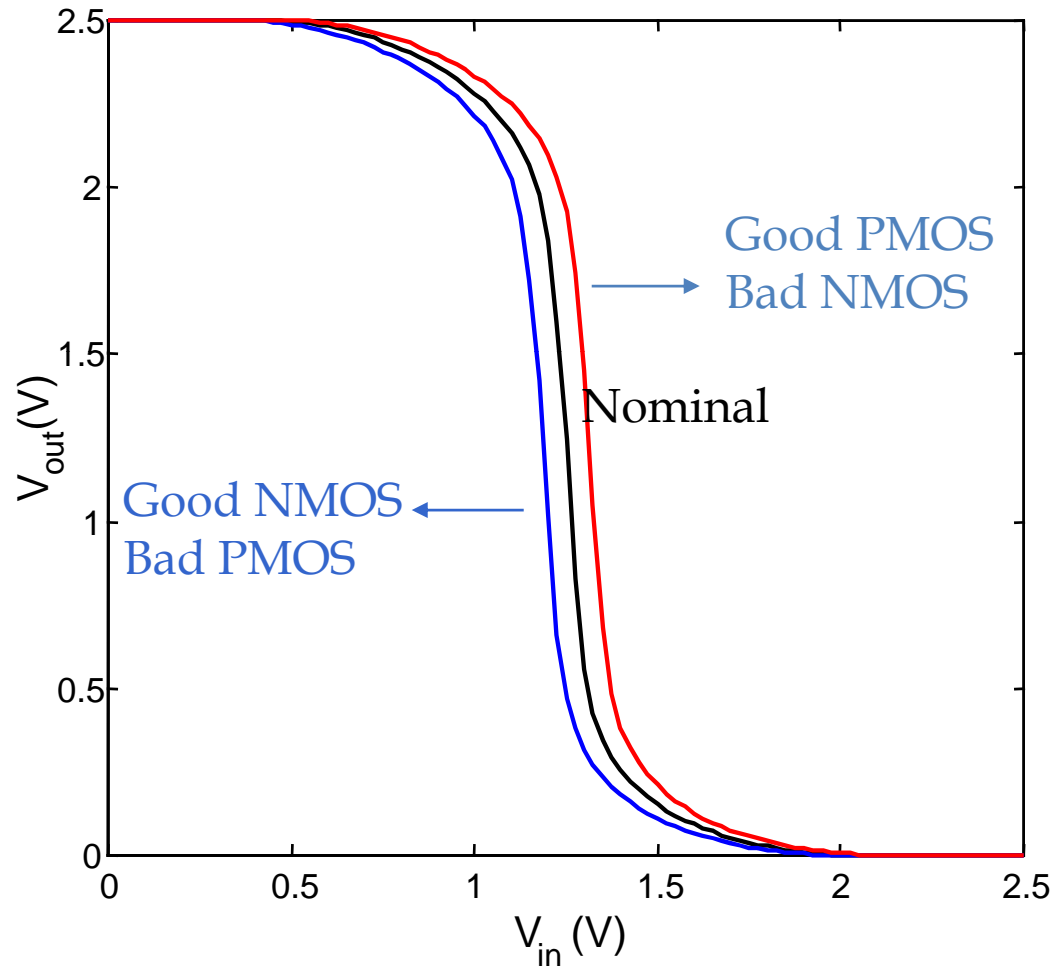
Gain as a function of VDD



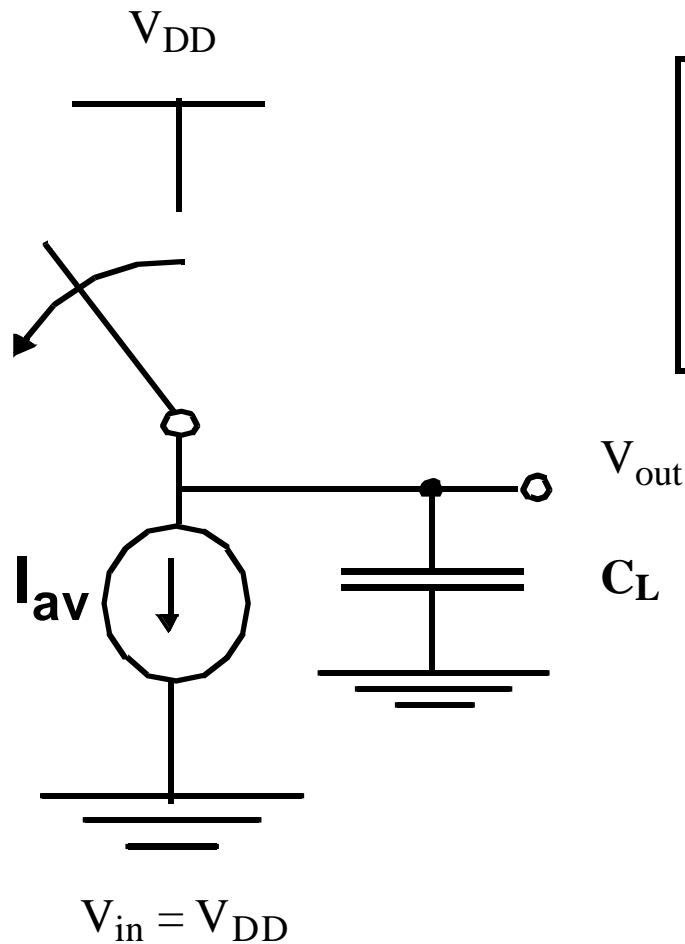
Simulated VTC



Impact of Process Variations



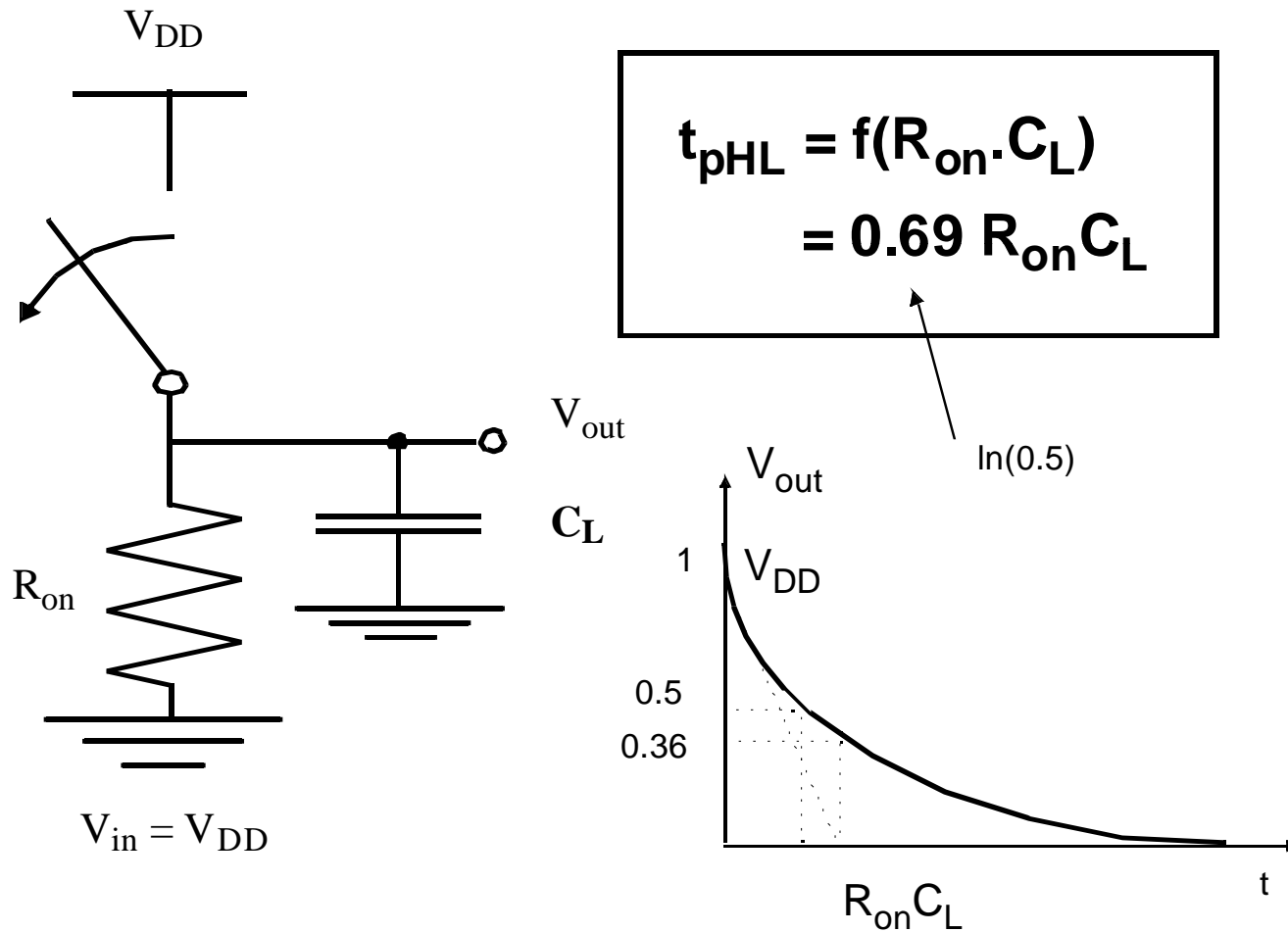
2. CMOS Inverter Propagation Delay Approach 1



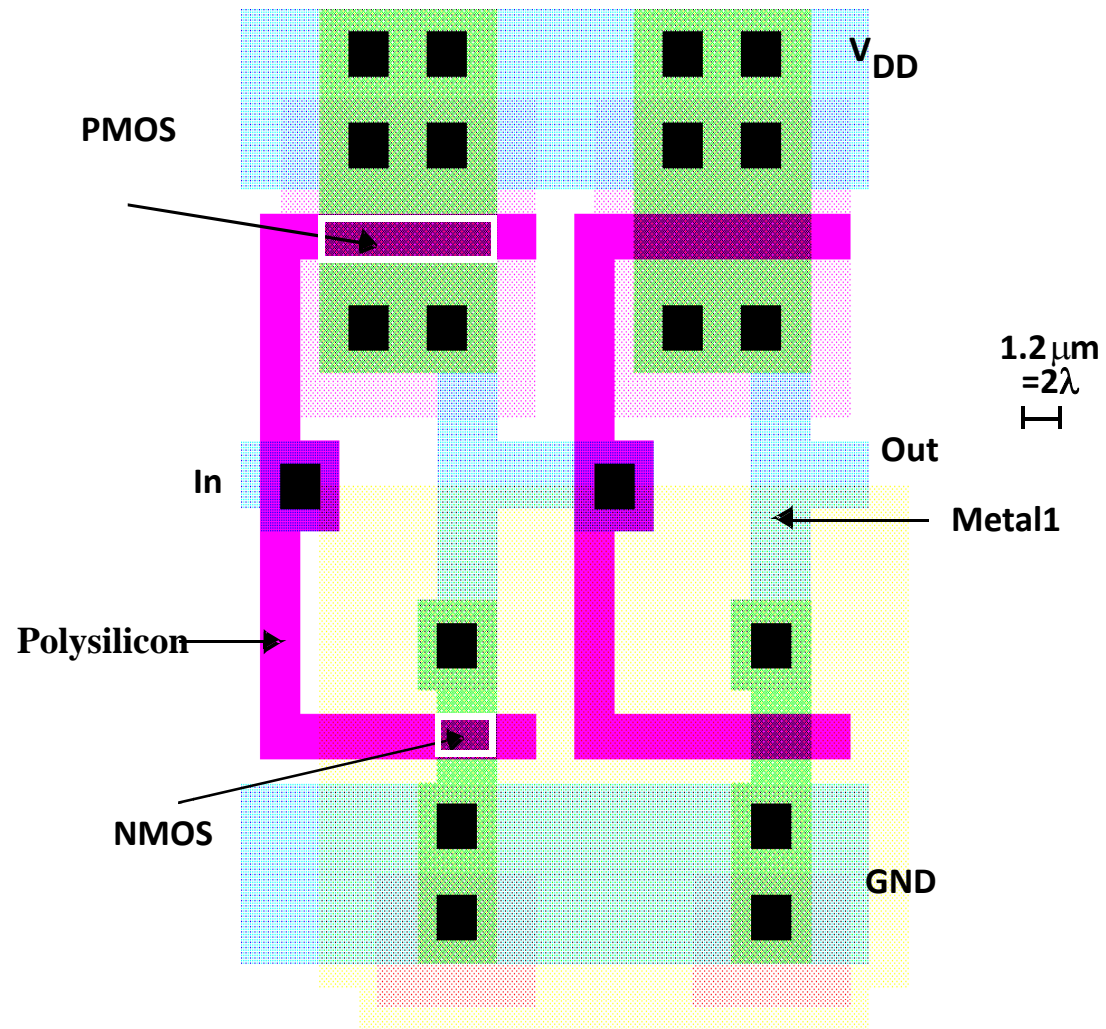
$$t_{pHL} = \frac{C_L V_{swing}/2}{I_{av}}$$

$$\sim \frac{C_L}{k_n V_{DD}}$$

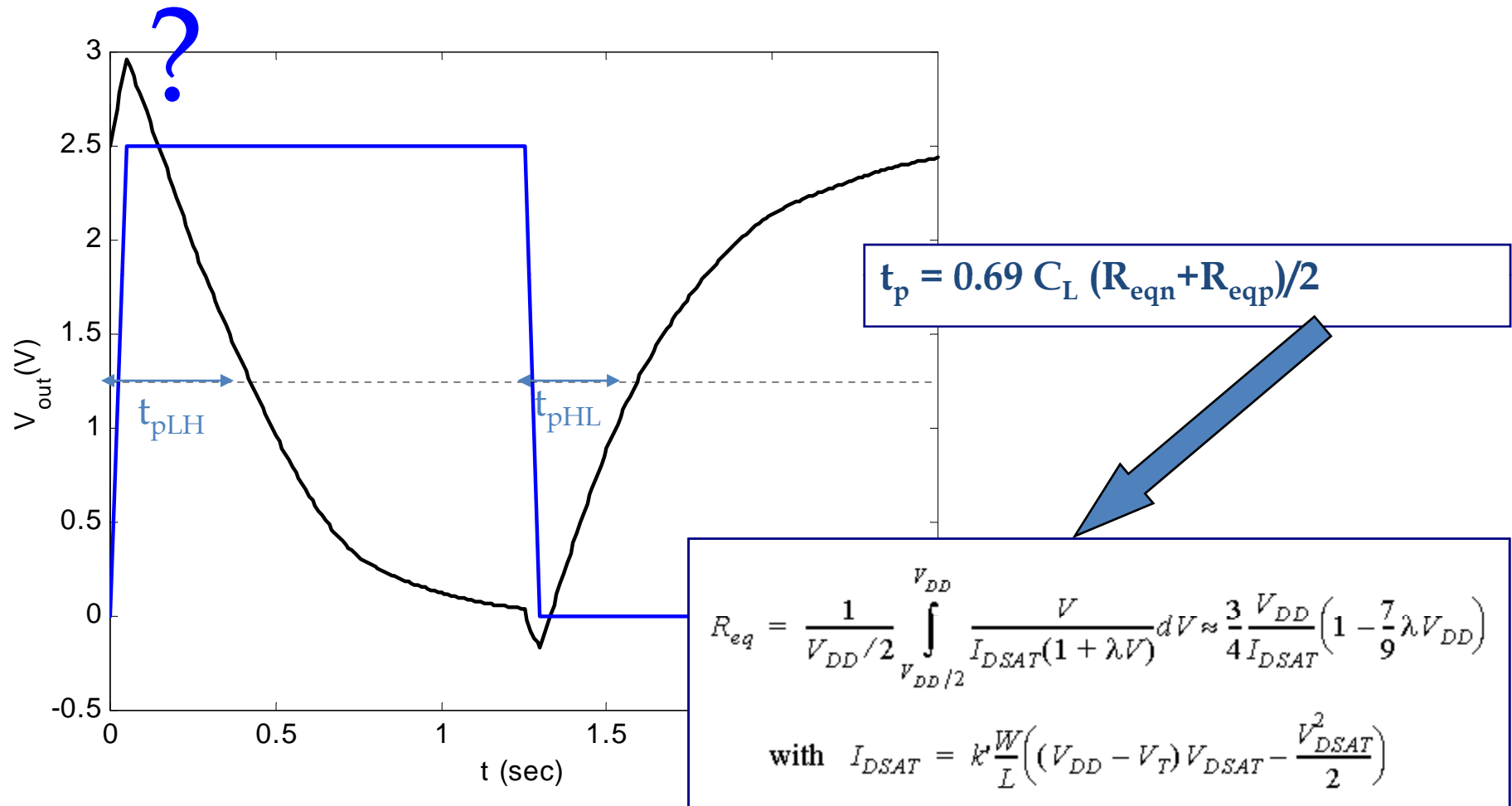
CMOS Inverter Propagation Delay Approach 2



CMOS Inverters



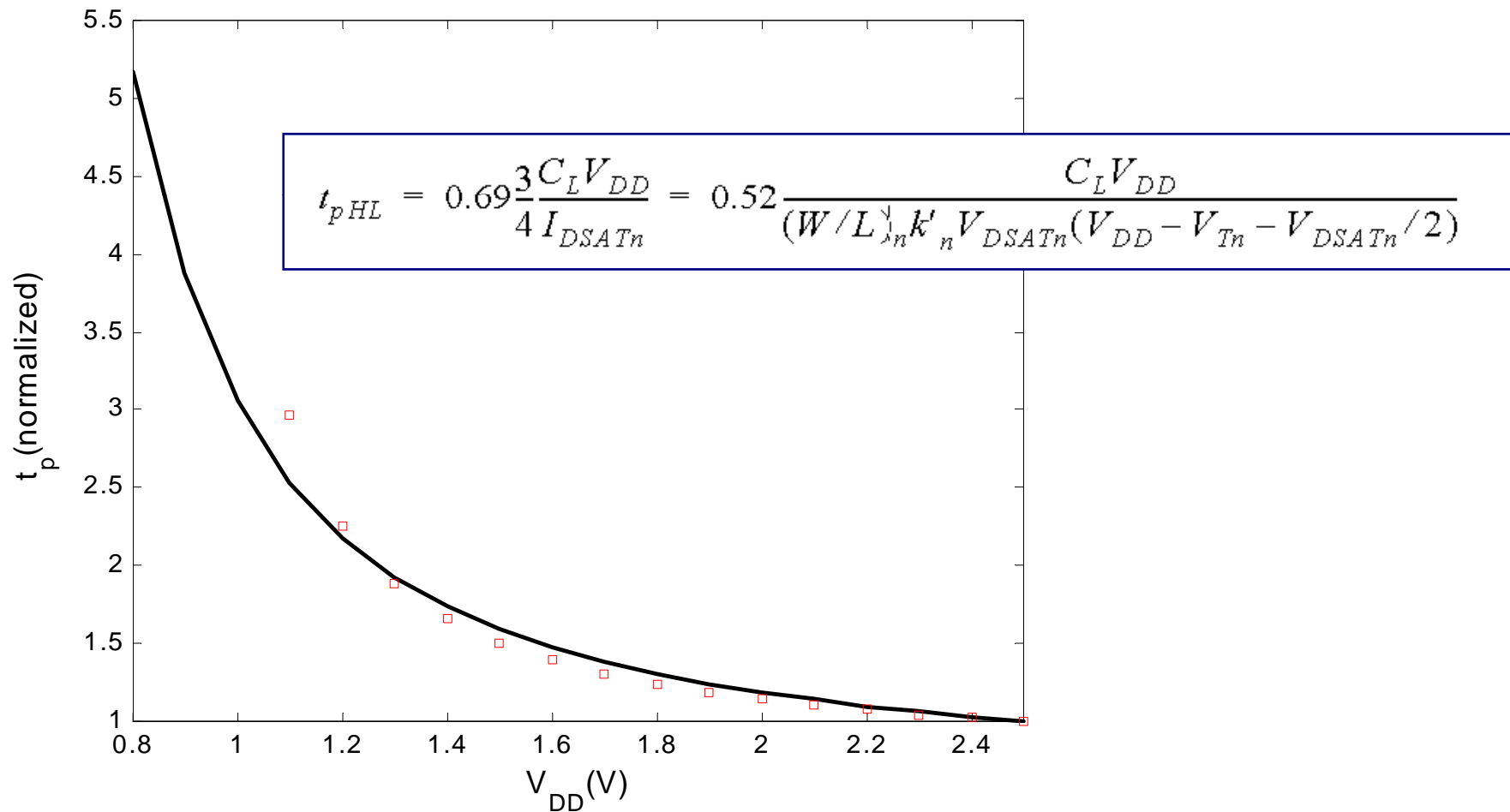
Transient Response



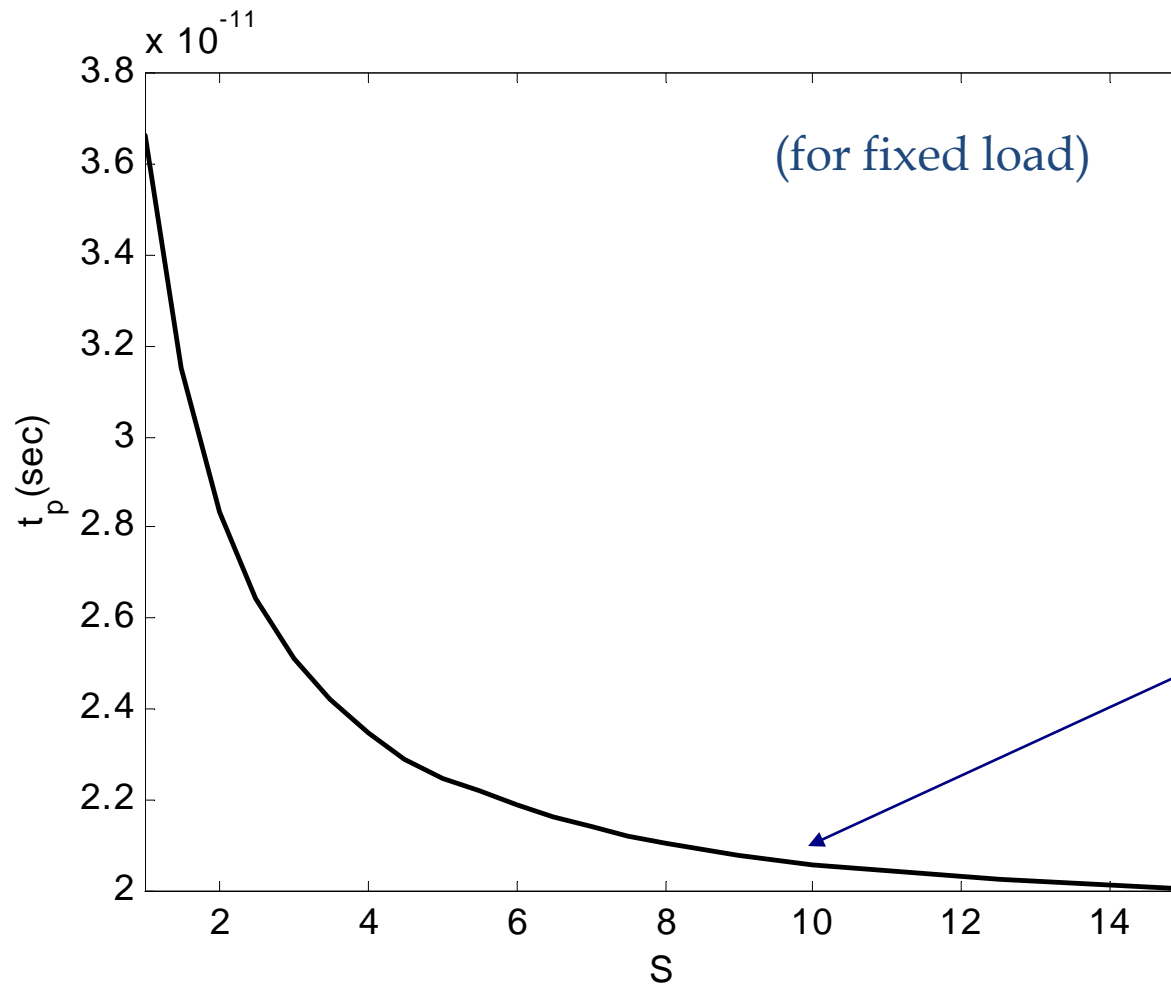
Design for Performance

- Keep capacitances small
- Increase transistor sizes
 - watch out for self-loading!
- Increase V_{DD} (????)

Delay as a function of V_{DD}

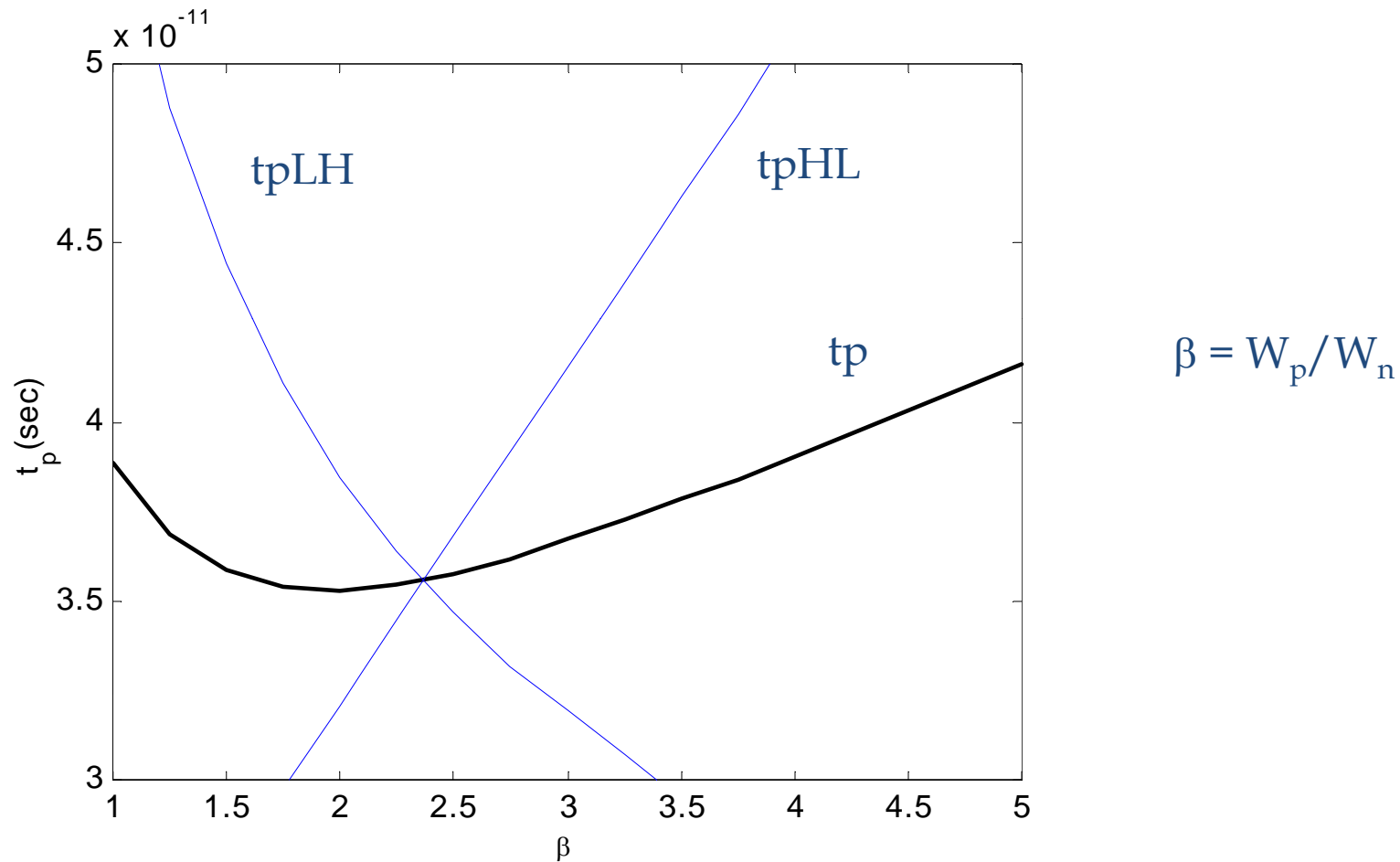


Device Sizing

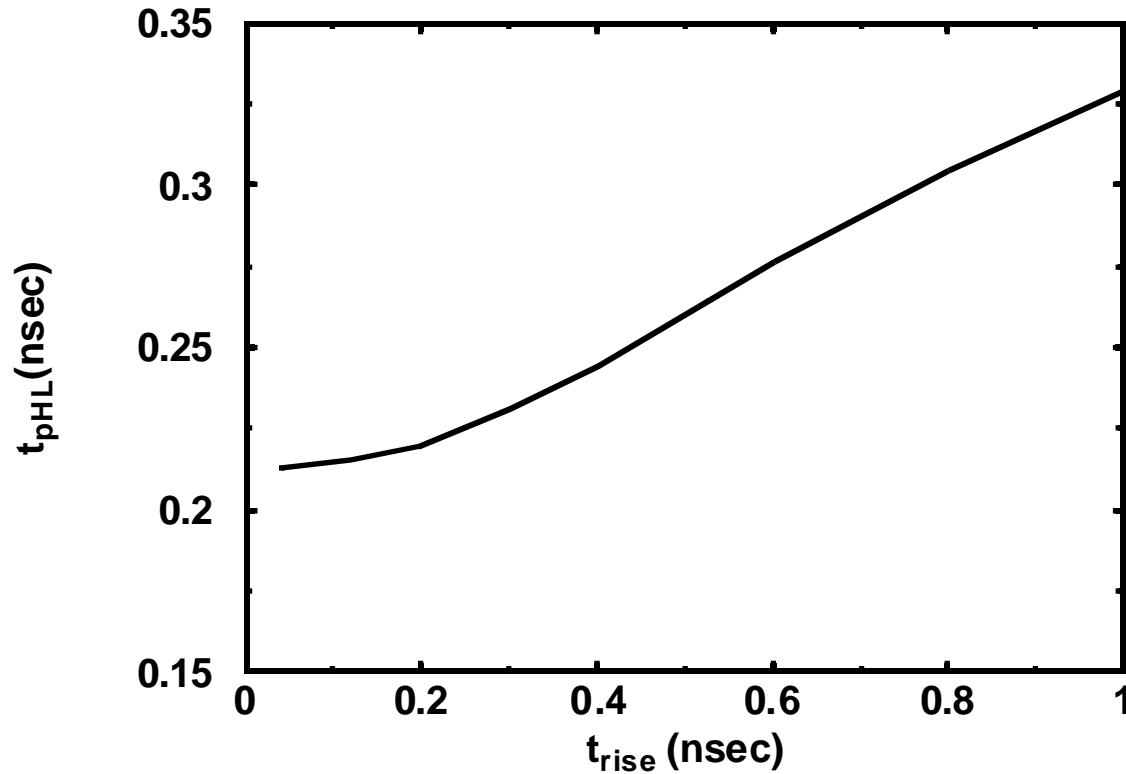


Self-loading effect:
Intrinsic capacitances
dominate

NMOS/PMOS ratio



Impact of Rise Time on Delay



$$t_{pHL} = \sqrt{t_{pHL(step)}^2 + (t_r/2)^2}$$

Delay Formula

$$\text{Delay} \sim R_W (C_{int} + C_L)$$

$$t_p = kR_W C_{int} (1 + C_L / C_{int}) = t_{p0} (1 + f / \gamma)$$

$$C_{int} = \gamma C_{gin} \text{ with } \gamma \approx 1$$

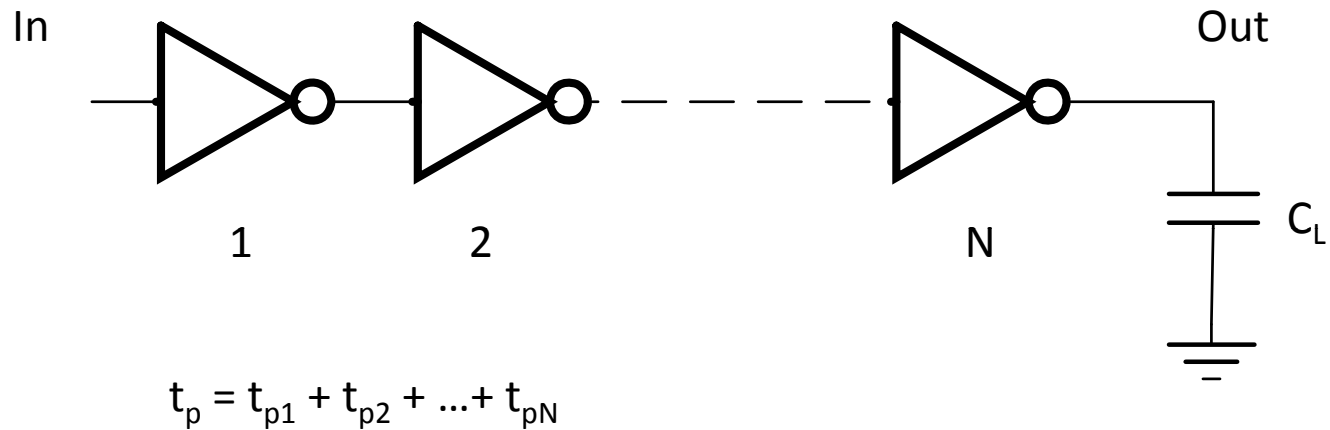
$$f = C_L / C_{gin} \text{ - effective fanout}$$

$$R = R_{unit} / W ; C_{int} = WC_{unit}$$

$$t_{p0} = 0.69 R_{unit} C_{unit}$$

3. Inverter Sizing

Apply to Inverter Chain



$$t_{pj} \sim R_{unit} C_{unit} \left(1 + \frac{C_{gin,j+1}}{\gamma C_{gin,j}} \right)$$

$$t_p = \sum_{j=1}^N t_{p,j} = t_{p0} \sum_{i=1}^N \left(1 + \frac{C_{gin,j+1}}{\gamma C_{gin,j}} \right), \quad C_{gin,N+1} = C_L$$

Optimal Tapering for Given N

Delay equation has N - 1 unknowns, $C_{gin,2} - C_{gin,N}$

Minimize the delay, find N - 1 partial derivatives

Result: $C_{gin,j+1}/C_{gin,j} = C_{gin,j}/C_{gin,j-1}$

Size of each stage is the geometric mean of two neighbors

- each stage has the same effective fanout (C_{out}/C_{in})
- each stage has the same delay $C_{gin,j} = \sqrt{C_{gin,j-1} C_{gin,j+1}}$

Optimum Delay and Number of Stages

When each stage is sized by f and has same eff. fanout f :

$$f^N = F = C_L / C_{gin,1}$$

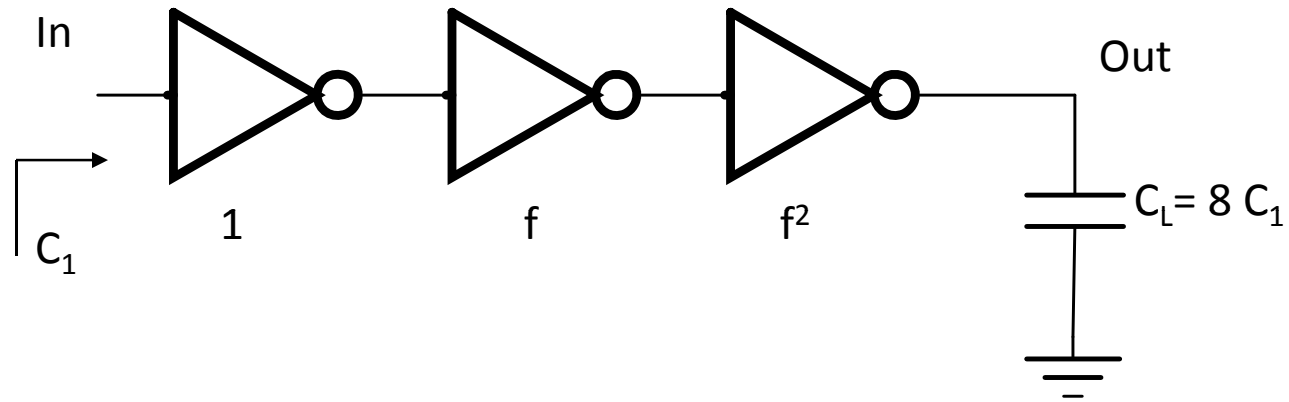
Effective fanout of each stage:

$$f = \sqrt[N]{F}$$

Minimum path delay

$$t_p = Nt_{p0} \left(1 + \sqrt[N]{F} / \gamma \right)$$

Example



C_L/C_1 has to be evenly distributed across $N = 3$ stages:

$$f = \sqrt[3]{8} = 2$$

Optimum Number of Stages

For a given load, C_L and given input capacitance C_{in}
Find optimal sizing f

$$C_L = F \cdot C_{in} = f^N C_{in} \quad \text{with} \quad N = \frac{\ln F}{\ln f}$$

$$t_p = N t_{p0} \left(F^{1/N} / \gamma + 1 \right) = \frac{t_{p0} \ln F}{\gamma} \left(\frac{f}{\ln f} + \frac{\gamma}{\ln f} \right)$$

$$\frac{\partial t_p}{\partial f} = \frac{t_{p0} \ln F}{\gamma} \cdot \frac{\ln f - 1 - \gamma/f}{\ln^2 f} = 0$$

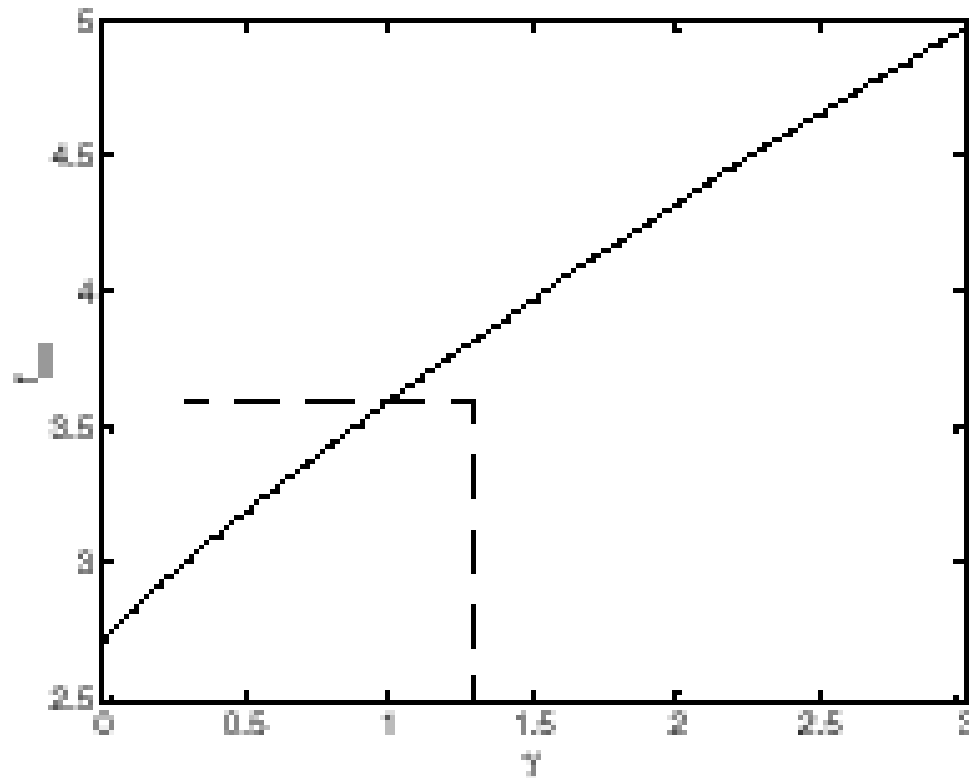
For $\gamma = 0$, $f = e$, $N = \ln F$

$$f = \exp(1 + \gamma/f)$$

Optimum Effective Fanout f

Optimum f for given process defined by γ

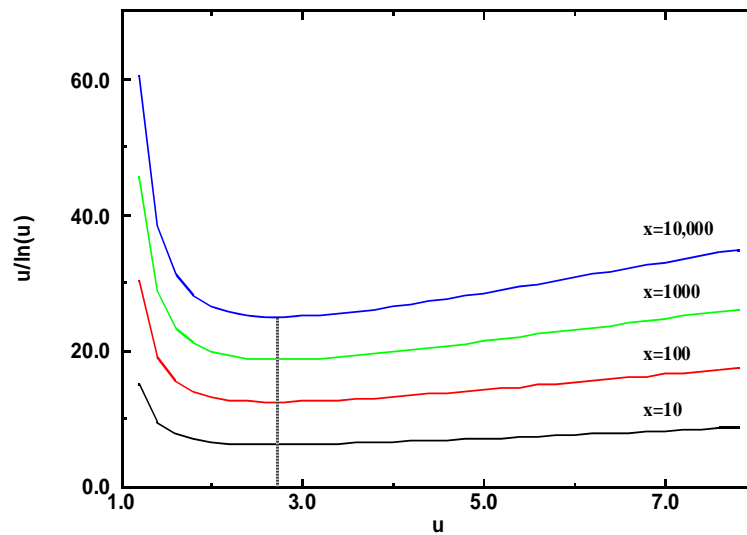
$$f = \exp(1 + \gamma/f)$$



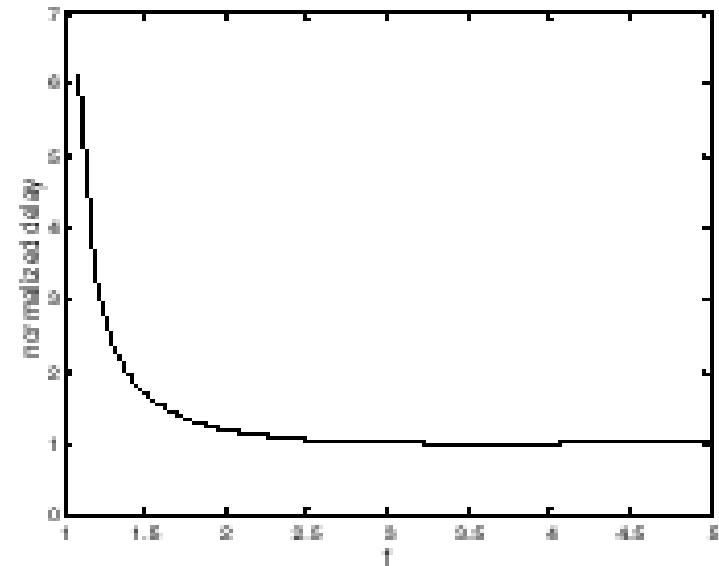
$f_{\text{opt}} = 3.6$
for $\gamma=1$

Impact of Self-Loading on t_p

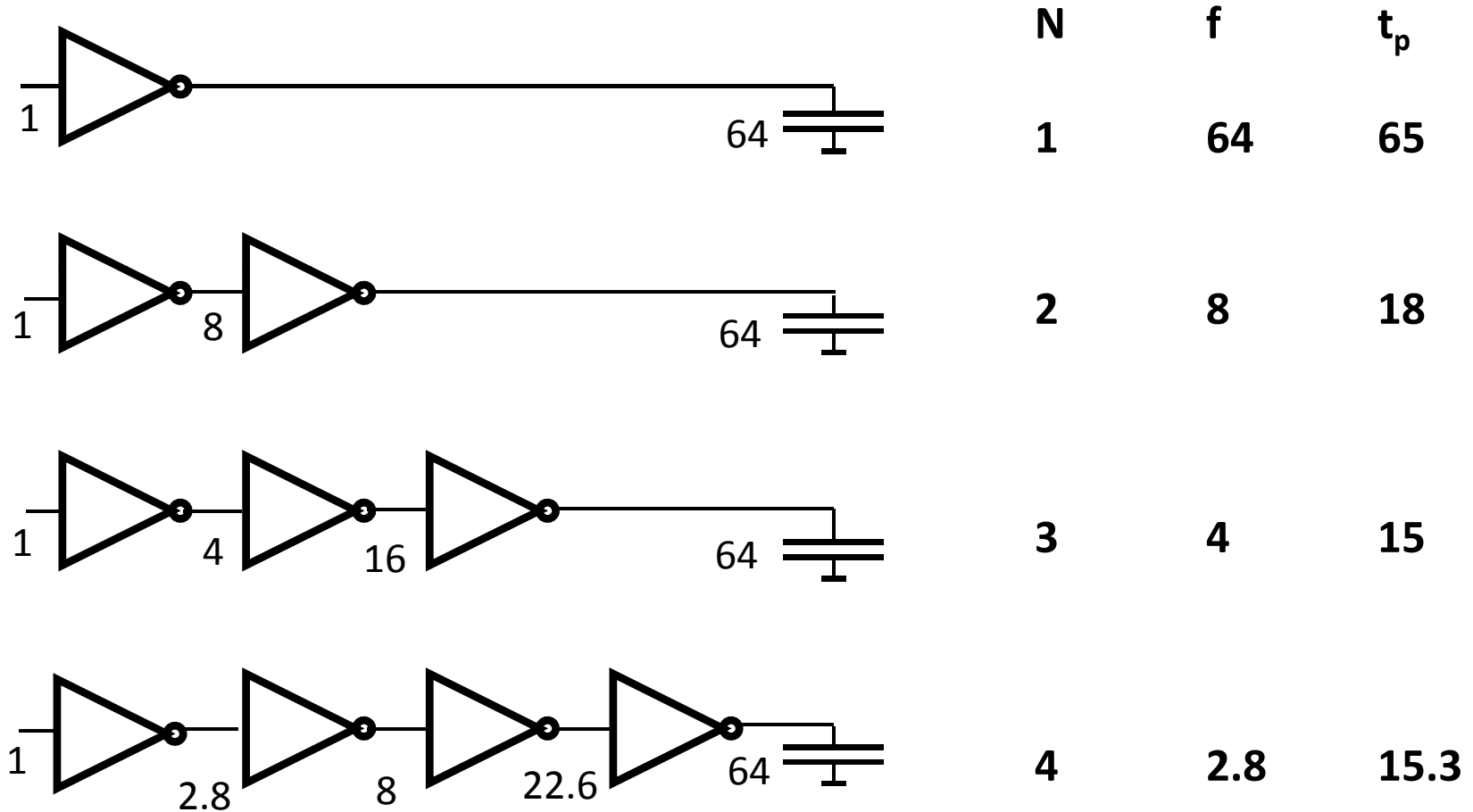
No Self-Loading, $\gamma=0$



With Self-Loading $\gamma=1$



Buffer Design



4. Power Dissipation

Where Does Power Go in CMOS?

- **Dynamic Power Consumption**

Charging and Discharging Capacitors

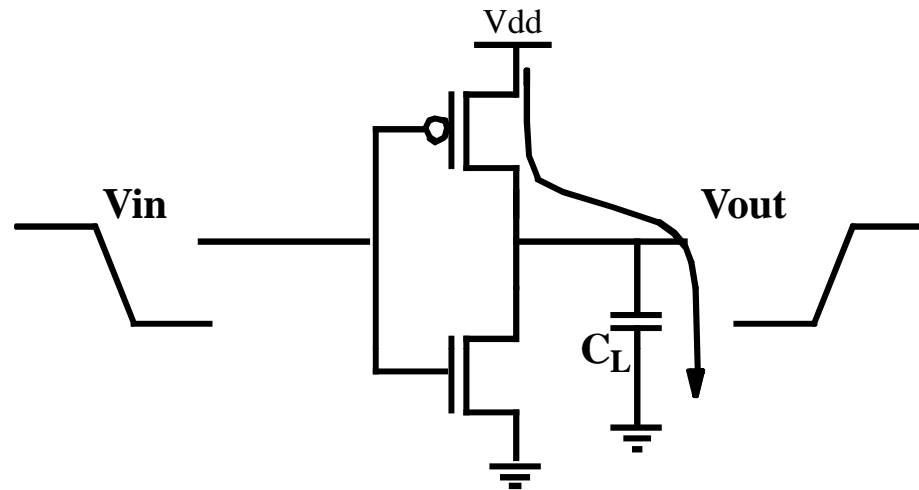
- **Short Circuit Currents**

Short Circuit Path between Supply Rails during Switching

- **Leakage**

Leaking diodes and transistors

Dynamic Power Dissipation

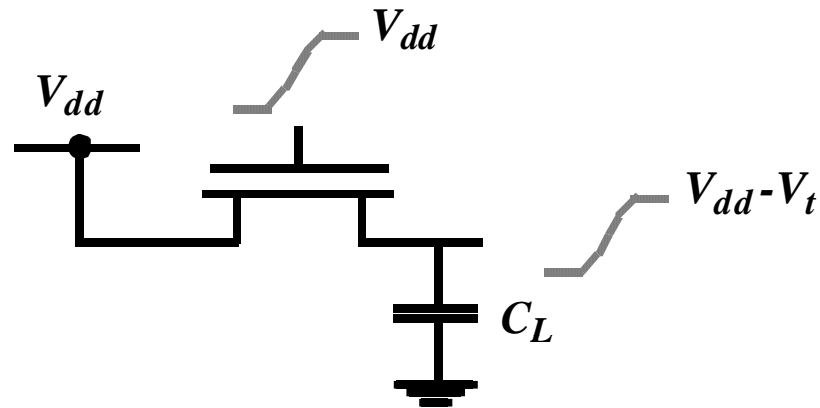


$$\text{Energy/transition} = C_L * V_{dd}^2$$

$$\text{Power} = \text{Energy/transition} * f = C_L * V_{dd}^2 * f$$

- Not a function of transistor sizes!
- Need to reduce C_L , V_{dd} , and f to reduce power.

Modification for Circuits with Reduced Swing

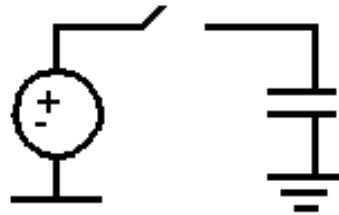


$$E_{0 \rightarrow 1} = C_L \cdot V_{dd} \cdot (V_{dd} - V_t)$$

- Can exploit reduced swing to lower power (e.g., reduced bit-line swing in memory)

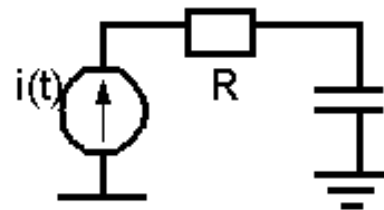
Adiabatic Charging

Charging a capacitor



$$CV_{dd}^2/2$$

Consider



$$v_c = \frac{1}{C} \cdot \int_0^T i dt = \frac{1}{C} \cdot I_{av} \cdot T \quad I_{av} = \frac{C \cdot v_c}{T}$$

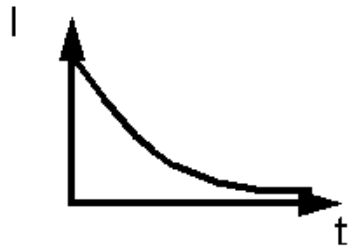
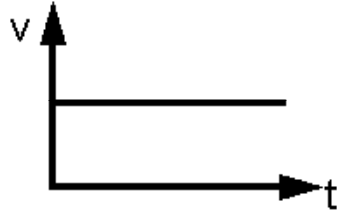
$$E_{dis} = R \cdot \int_0^T i^2(t) dt \geq R \cdot \int_0^T I_{av}^2 dt = R \cdot I_{av}^2 \cdot T = \frac{RC}{T} \cdot C \cdot V_c^2$$



Adiabatic Charging

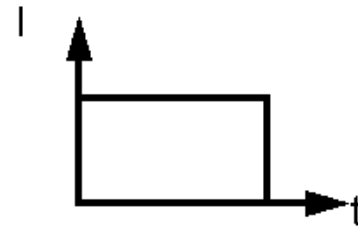
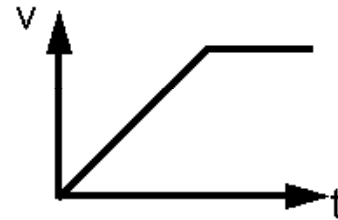
$$V_I = RI + V_c = RC \frac{dv}{dt} + V_c$$

$V_I = \text{cst} \rightarrow$ Exponential current



$$E_R = CV_c^2 / 2$$

$I = I_{av} \rightarrow$ Linear ramp on V_I



wins if $T > 2RC$

mimimal energy

$$E_R = RC/T CV_c^2$$

Node Transition Activity and Power

- Consider switching a CMOS gate for N clock cycles

$$E_N = C_L \cdot V_{dd}^2 \cdot n(N)$$

E_N : the energy consumed for N clock cycles

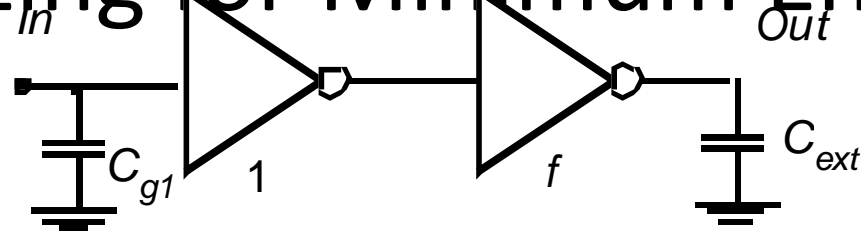
$n(N)$: the number of 0->1 transition in N clock cycles

$$P_{avg} = \lim_{N \rightarrow \infty} \frac{E_N}{N} \cdot f_{clk} = \left(\lim_{N \rightarrow \infty} \frac{n(N)}{N} \right) \cdot C_L \cdot V_{dd}^2 \cdot f_{clk}$$

$$\alpha_{0 \rightarrow 1} = \lim_{N \rightarrow \infty} \frac{n(N)}{N}$$

$$P_{avg} = \alpha_{0 \rightarrow 1} \cdot C_L \cdot V_{dd}^2 \cdot f_{clk}$$

Transistor Sizing for Minimum Energy



- Goal: Minimize Energy of whole circuit
 - Design parameters: f and V_{DD}
 - $t_p \leq t_{pref}$ of circuit with $f=1$ and $V_{DD} = V_{ref}$

$$t_p = t_{p0} \left(\left(1 + \frac{f}{\gamma} \right) + \left(1 + \frac{F}{f\gamma} \right) \right)$$

$$t_{p0} \propto \frac{V_{DD}}{V_{DD} - V_{TE}}$$

Transistor Sizing (2)

- Performance Constraint ($\gamma=1$)

$$\frac{t_p}{t_{pref}} = \frac{t_{p0}}{t_{p0ref}} \frac{\left(2 + f + \frac{F}{f}\right)}{(3 + F)} = \frac{V_{DD}}{V_{ref}} \frac{V_{ref} - V_{TE}}{V_{DD} - V_{TE}} \frac{\left(2 + f + \frac{F}{f}\right)}{(3 + F)} = 1$$

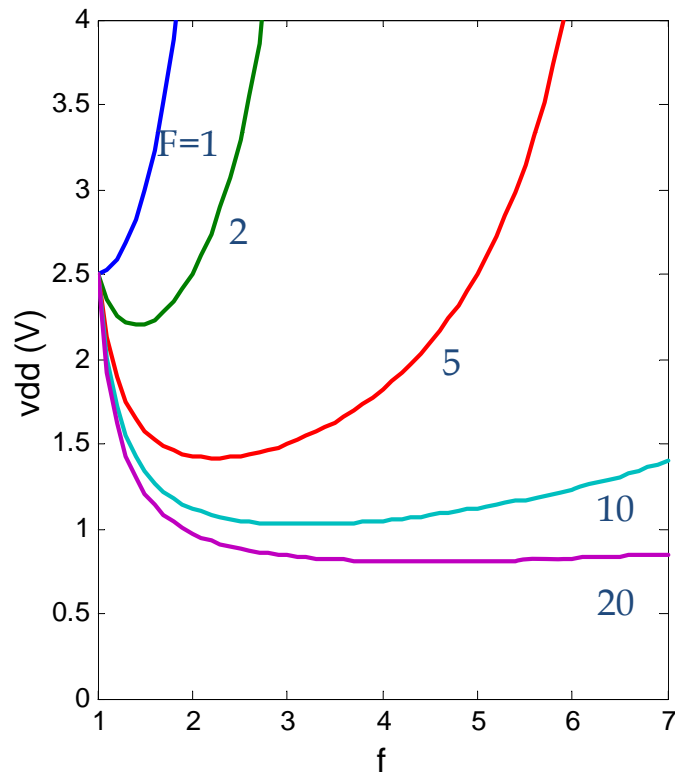
- Energy for single Transition

$$E = V_{DD}^2 C_{g1} [(1 + \gamma)(1 + f) + F]$$

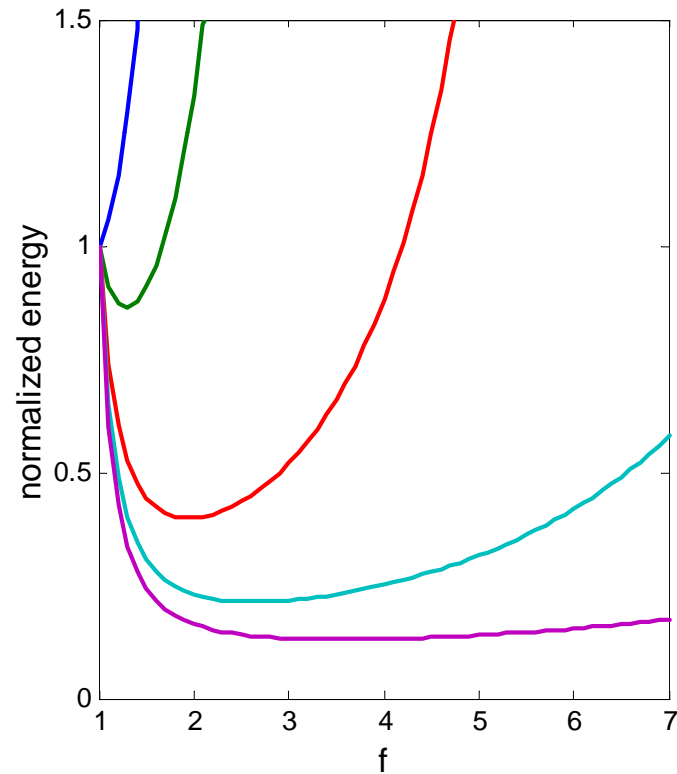
$$\frac{E}{E_{ref}} = \left(\frac{V_{DD}}{V_{ref}}\right)^2 \left(\frac{2 + 2f + F}{4 + F}\right)$$

Transistor Sizing (3)

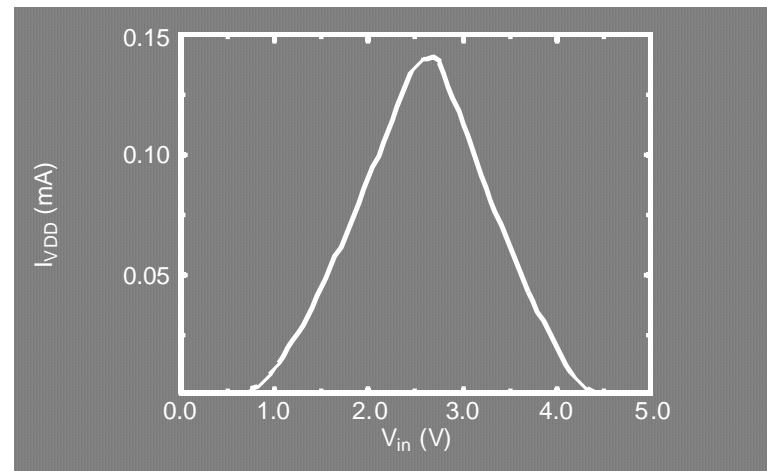
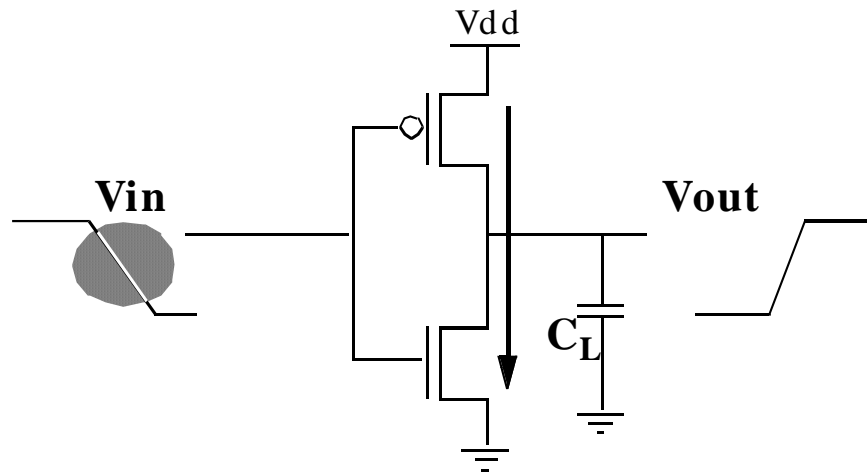
$$V_{DD} = f(f)$$



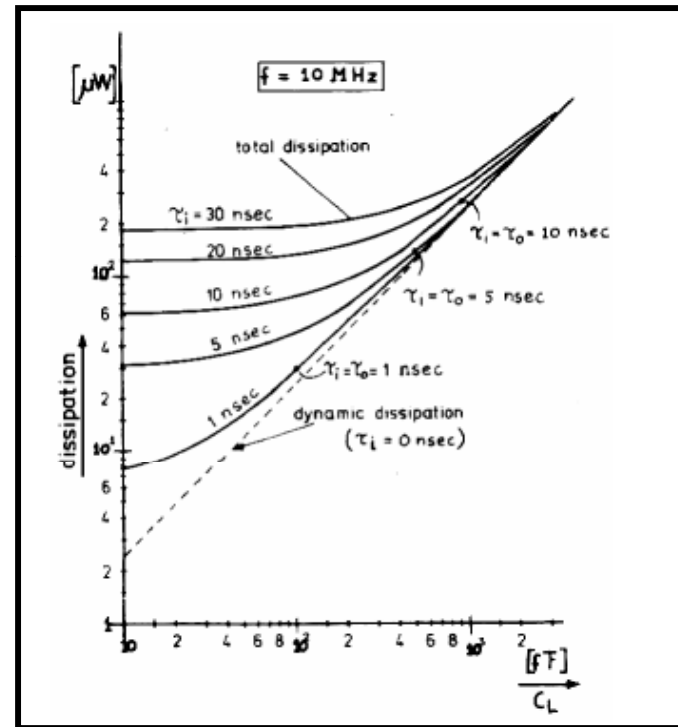
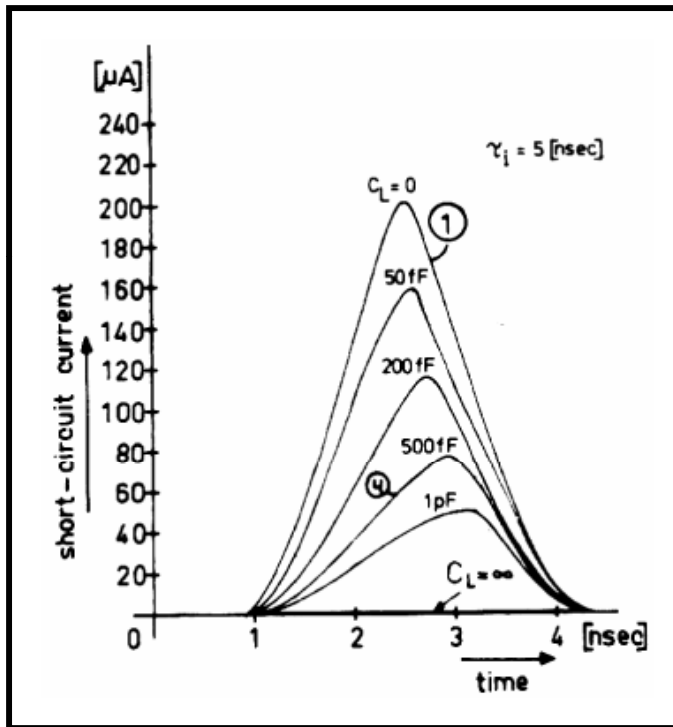
$$E/E_{ref} = f(f)$$



Short Circuit Currents

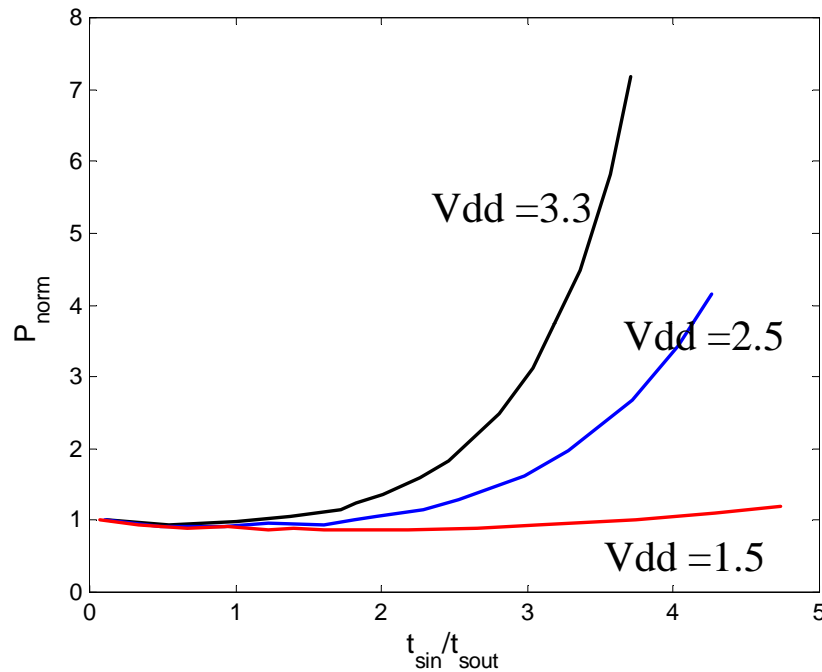


How to keep Short-Circuit Currents Low?



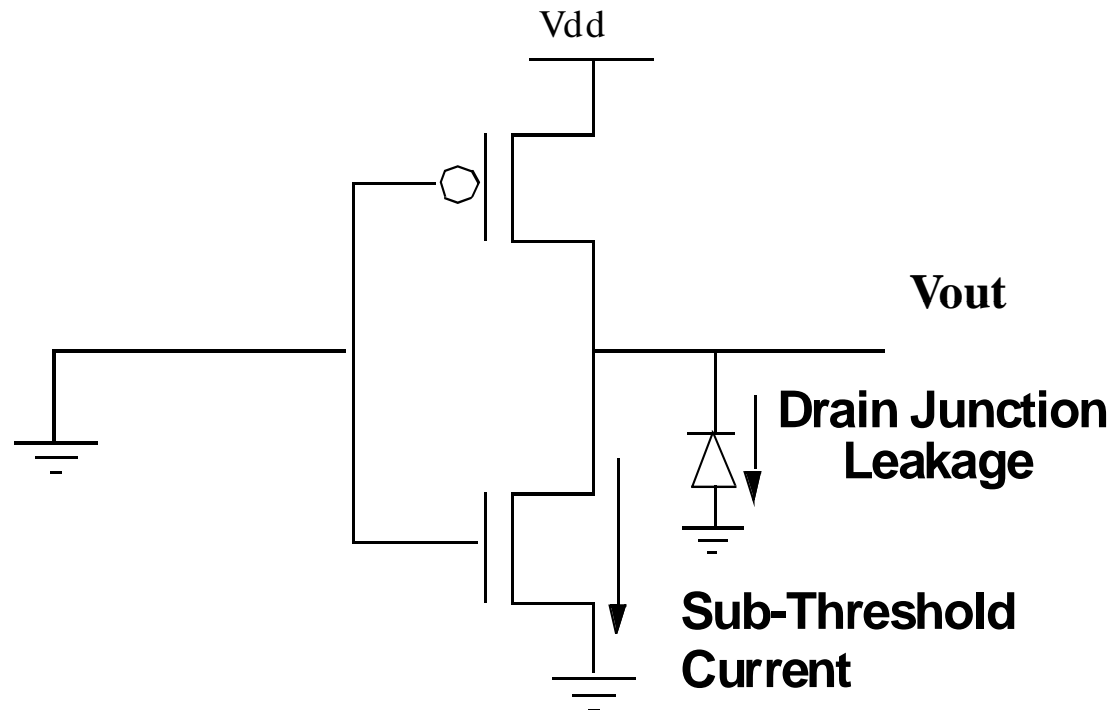
Short circuit current goes to zero if $t_{\text{fall}} \gg t_{\text{rise}}$,
but can't do this for cascade logic, so ...

Minimizing Short-Circuit Power



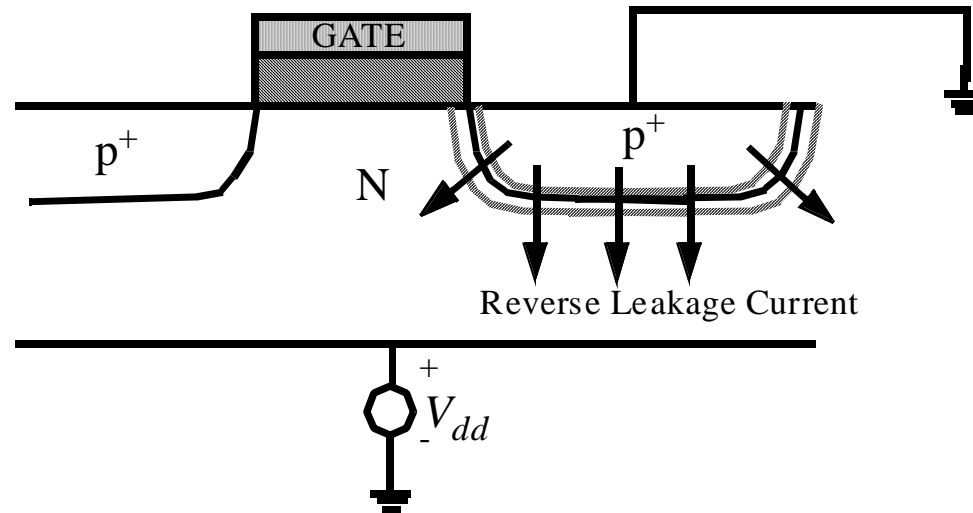
- Keep the input and output rise/fall times the same (< 10% of Total Consumption)
from [Veendrick84]
(*IEEE Journal of Solid-State Circuits*, August 1984)
- If $V_{\text{dd}} < V_{\text{tn}} + |V_{\text{tp}}|$ then short-circuit power can be *eliminated!*

Leakage



Sub-threshold current one of most compelling issues in low-energy circuit design!

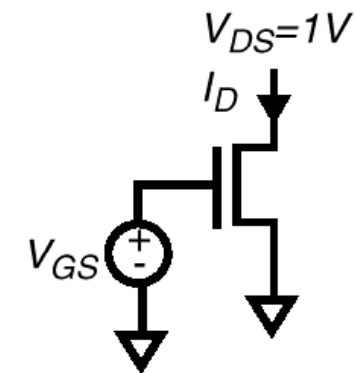
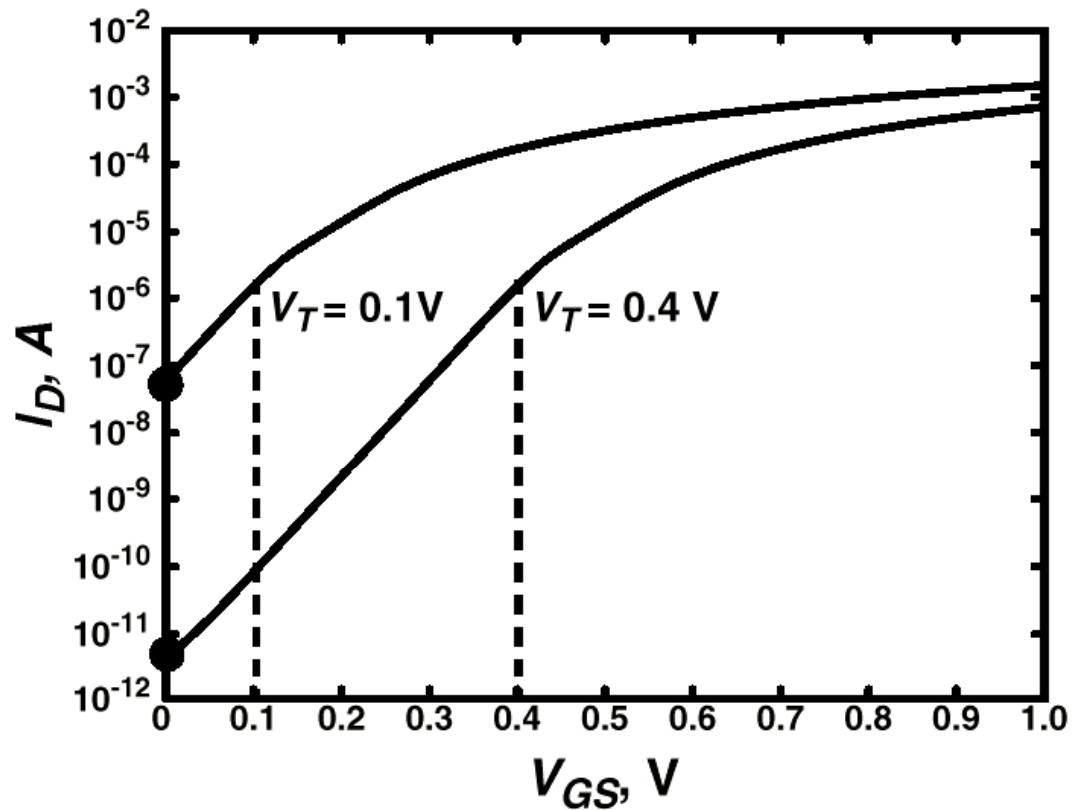
Reverse-Biased Diode Leakage



$$I_{DL} = J_S \times A$$

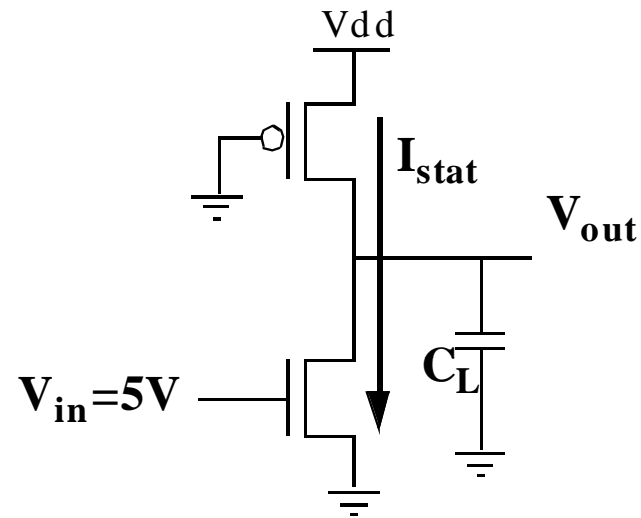
JS = 10-100 pA/μm² at 25 deg C for 0.25μm CMOS
JS doubles for every 9 deg C!

Subthreshold Leakage Component



- Leakage control is critical for low-voltage operation

Static Power Consumption



$$P_{stat} = P_{(In=1)} \cdot V_{dd} \cdot I_{stat}$$

Wasted energy ...

Should be avoided in almost all cases,
but could help reducing energy in others (e.g. sense amps)

Principles for Power Reduction

- Prime choice: Reduce voltage!
 - Recent years have seen an acceleration in supply voltage reduction
 - Design at very low voltages still open question (0.6 ... 0.9 V by 2010!)
- Reduce switching activity
- Reduce physical capacitance
 - Device Sizing: for $F=20$
 - $f_{opt}(\text{energy})=3.53, f_{opt}(\text{performance})=4.47$

5. Impact of Technology Scaling

Goals of Technology Scaling

- Make things cheaper:
 - Want to sell more functions (transistors) per chip for the same money
 - Build same products cheaper, sell the same part for less money
 - Price of a transistor has to be reduced
- But also want to be faster, smaller, lower power

Technology Scaling

- Goals of scaling the dimensions by 30%:
 - Reduce gate delay by 30% (increase operating frequency by 43%)
 - Double transistor density
 - Reduce energy per transition by 65% (50% power savings @ 43% increase in frequency)
- Die size used to increase by 14% per generation
- Technology generation spans 2-3 years